Validation Report

Virginia, SPS-1 Task Order 15, CLIN 2 December 2 thru 4, 2008

1 Executive Summary	1
2 Corrective Actions Recommended	3
3 Post Calibration Analysis	3
3.1 Temperature-based Analysis	6
3.2 Speed-based Analysis	8
3.3 Classification Validation	10
3.4 Evaluation by ASTM E-1318 Criteria	11
4 Pavement Discussion	11
4.1 Profile Analysis	11
4.2 Distress Survey and Any Applicable Photos	13
4.3 Vehicle-pavement Interaction Discussion	13
5 Equipment Discussion	
5.1 Pre-Evaluation Diagnostics	14
5.2 Calibration Process	14
5.2.1 Calibration Iteration 1	
5.3 Summary of Traffic Sheet 16s	15
5.4 Projected Maintenance/Replacement Requirements	16
6 Pre-Validation Analysis	17
6.1 Temperature-based Analysis	21
6.2 Speed-based Analysis	23
6.3 Classification Validation	24
6.4 Evaluation by ASTM E-1318 Criteria	25
6.5 Prior Validations	26
7 Data Availability and Quality	27
8 Data Sheets	31
9 Updated Handout Guide and Sheet 17	31
10 Updated Sheet 18	31
11 Traffic Sheet 16(s)	31

List of Tables

Table 1-1 - Post-Validation Results – 510100 – 04-Dec-2008	1
Table 1-2 - Results Based on ASTM E-1318-02 Test Procedures	2
Table 3-1 - Post-Validation Results - 510100 - 04-Dec-2008	3
Table 3-2 - Post-Validation Results by Temperature Bin – 510100 – 04-Dec-2008	6
Table 3-3 - Post-Validation Results by Speed Bin – 510100 – 04-Dec-2008	8
Table 3-4 - Truck Misclassification Percentages for 510100 – 04-Dec-2008	. 10
Table 3-5 - Truck Classification Mean Differences for 510100 – 04-Dec-2008	. 10
Table 3-6 - Results of Validation Using ASTM E-1318-02 Criteria	. 11
Table 4-1 - Thresholds for WIM Index Values	. 12
Table 4-2 - WIM Index Values – 510100 –23-Oct-2008	. 13
Table 5-1 - Initial System Parameters - 510100 - 02-Dec-2008	. 14
Table 5-2 - Calibration Iteration 1 - Change in Parameters - 510100 - 03-Dec-2008	. 15
Table 5-3 - Calibration Iteration 1 – Results – 510100 – 03-Dec-2008 (01:45 PM)	. 15
Table 5-4 - Classification Validation History – 510100 – 04-Dec-2008	. 16
Table 5-5 - Weight Validation History – 510100 – 04-Dec-2008	. 16
Table 6-1 - Calibration Factor Change – 510100 – since 25-Jul-2007	. 18
Table 6-2 - Pre-Validation Results – 510100 – 02-Dec-2008	. 18
Table 6-3 - Pre-Validation Results by Temperature Bin – 510100 – 02-Dec-2008	. 21
Table 6-4 - Pre-Validation Results by Speed Bin – 510100 – 02-Dec-2008	. 23
Table 6-5 - Truck Misclassification Percentages for 510100 – 02-Dec-2008	. 24
Table 6-6 - Truck Classification Mean Differences for 510100 – 02-Dec-2008	. 25
Table 6-7 - Results of Validation Using ASTM E-1318-02 Criteria	. 25
Table 6-8 - Last Validation Final Results – 510100 – 25-Jul-2007	. 26
Table 6-9 – Last Validation Results by Temperature Bin – 510100 – 25-Jul-2007	. 27
Table 6-10 - Last Validation Results by Speed Bin – 510100 – 25-Jul-2007	. 27
Table 7-1 - Amount of Traffic Data Available 510100 – 02-Dec-2008	. 28
Table 7-2 - GVW Characteristics of Major sub-groups of Trucks – 510100 – 04-Dec-	
2008	. 29

List of Figures

Figure 3-1 - Post-Validation Speed-Temperature Distribution – 510100 – 04-Dec-2008. 4
Figure 3-2 - Post-Validation GVW Percent Error vs. Speed – 510100 – 04-Dec-2008 5
Figure 3-3 - Post-Validation GVW Percent Error vs. Temperature – 510100 – 04-Dec-
20085
Figure 3-4 - Post-Validation Spacing vs. Speed - 510100 - 04-Dec-2008 6
Figure 3-5 - Post-Validation GVW Percent Error vs. Temperature by Truck – 510100 –
04-Dec-2008
Figure 3-6 - Post-Validation Steering Axle Error vs. Temperature by Group – 510100 –
04-Dec-2008
Figure 3-7 - Post-Validation GVW Percent Error vs. Speed by Truck – 510100 – 04-Dec-
20089
Figure 3-8 - Post-Validation Steering Axle Percent Error vs. Speed by Group – 510100 –
04-Dec-20089
Figure 5-1 - Calibration Iteration 1 - GVW Percent Error vs. Speed Group - 510100 - 03-
Dec-2008 (01:45 PM)
Figure 5-2 - 510100 Example nut in leading WIM Sensor 2-Dec-2008
Figure 5-3 - 510100 Example nut in trailing WIM Sensor 2-Dec-2008
Figure 6-1 - Pre-Validation Speed-Temperature Distribution – 510100 – 02-Dec-2008. 19
Figure 6-2 - Pre-Validation GVW Percent Error vs. Speed – 510100 – 02-Dec-2008 20
Figure 6-3 - Pre-Validation GVW Percent Error vs. Temperature – 510100 – 02-Dec-
2008
Figure 6-4 - Pre-Validation Spacing vs. Speed - 510100 – 02-Dec-2008
Figure 6-5 - Pre-Validation GVW Percent Error vs. Temperature by Truck – 510100 –
02-Dec-2008
Figure 6-6 - Pre-Validation Steering Axle Error vs. Temperature by Group – 510100 –
02-Dec-2008
Figure 6-7 - Pre-Validation GVW Percent Error vs. Speed Group - 510100 -02-Dec-2008
23
Figure 6-8 - Pre-Validation Steering Axle Percent Error vs. Speed Group - 510100 -02-
Dec-200824
Figure 6-9 - Last Validation GVW Percent Error vs. Speed – 510100 – 25-Jul-2007 26
Figure 7-1 - Expected GVW Distribution Class 9 – 510100 – 04-Dec-2008
Figure 7-2 - Expected GVW Distribution Class 5 – 510100 – 04-Dec-2008
Figure 7-3 - Expected Vehicle Distribution – 510100 – 04-Dec-2008 30

1 Executive Summary

A visit was made to the Virginia 0100 on December 2 thru 4, 2008 for the purposes of conducting a validation of the WIM system located on US 29 at approximately 8 miles north of Danville on the US 29 Bypass. The SPS-1 is located in the righthand, southbound lane of a four-lane divided facility. The posted speed limit at this location is 65 mph. The LTPP lane is one of 2 lanes instrumented at this site. This report discusses the validation of the LTPP lane only. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This site is located approximately 500 feet downstream from a previous location. This is the third validation visit to this location. The site was installed on November 1 to 4, 2006 by International Road Dynamics Inc..

This site demonstrates the ability to produce research quality loading data under the observed conditions. The classification data is also of research quality for Traffic Monitoring Guide Classes.

The site is instrumented with bending plate sensors and iSINC electronics. It is installed in portland cement concrete, 424 feet long. The WIM sensors are 313 feet from the asphalt to concrete pavement transition. The LTPP Lane is identified as Lane number 1 by the controller.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 76,510 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 65,250 lbs., the "partial" truck.

The validation speeds ranged from 52 to 64 miles per hour. The pavement temperatures ranged from 29 to 54 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was not achieved.

Table 1-1 - Post-Validation Results – 510100 – 04-Dec-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$1.5 \pm 5.0\%$	Pass
Tandem axles	±15 percent	$1.2 \pm 5.8\%$	Pass
GVW	±10 percent	$1.0 \pm 3.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: ea Checked: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions

significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. Profile data was collected by the Regional Support Contractor on October 23, 2008. The upper threshold of the WIM index was not exceeded.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 - Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: ea Checked: bko

Upon our arrival at the site, we found the system parameters were not the same as we left them at the conclusion of our last validation on July 25, 2007. The sensors were remotely calibrated using the front axle values December 1, 2008 after equipment maintenance.

This site needs three years of data to meet the goal of five years of research quality data assuming that a sufficient quantity of data exists for 2008.

2 Corrective Actions Recommended

It was discovered on December 02, 2008 that the fastening bolts for both weigh pads were exposed. The bolts need to be cleaned and the silicon replaced around them before winter.

During the Post-Validation we were required to reset the system due to a "Class 14 downstream loop only" problem. IRD was contacted and recommended the reset. As this has not been the first time we have seen this problem, the Regions should be advised to review the number of Class 14 errors found within the data submitted to see if this is a significant problem.

3 Post Calibration Analysis

This final analysis is based on test runs conducted December 04, 2008 from early morning through late afternoon at test site 510100 on US 29. This SPS-1 site is at milepost 12.8 on the southbound, righthand lane of a four-lane divided facility. No autocalibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 76,510 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 65,250 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 52 to 64 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 29 to 54 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

The statistics in Table 3-1 indicates that the loading data meets the conditions for research quality data.

Table 3-1 - Post-Validation Results - 510100 - 04-Dec-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$1.5 \pm 5.0\%$	Pass
Tandem axles	±15 percent	$1.2 \pm 5.8\%$	Pass
GVW	±10 percent	$1.0 \pm 3.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	0.0 ± 0.1 ft	Pass
		D 1	Cl 1 . 1 . 1 . 1 .

Prepared: ea Checked: bko

The test runs were conducted primarily during the early morning and late afternoon, resulting in a reasonable range of pavement temperatures. The runs were conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and three temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs due to limits on the temperature range.

The three speed groups were divided as follows: Low speed -52 to 57 mph, Medium speed -58 to 61 mph and High speed -62 + mph. The three temperature groups were created by splitting the runs between those at 29 to 36 degrees Fahrenheit for Low temperature, 37 to 46 degrees Fahrenheit for Medium temperature and 47 to 54 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

70 66 Speed (mph) ocomb. 60 56 52 30 35 45 40 50 55 Temperature (F) Prepared: bko Checked: ea

Figure 3-1 - Post-Validation Speed-Temperature Distribution – 510100 – 04-Dec-2008

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. It can be seen from Figure 3-2 that the equipment generally overestimates GVW errors at all speeds. Variability in error is greater at low and medium speed when compared to high speed.



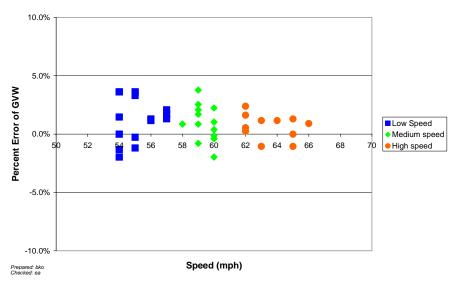


Figure 3-2 - Post-Validation GVW Percent Error vs. Speed – 510100 – 04-Dec-2008

Figure 3-3 shows the relationship between temperature and GVW percentage error. It can be seen from Figure 3-3 that the equipment generally overestimates GVW errors through the entire temperature range. Variability is greater at high temperature.

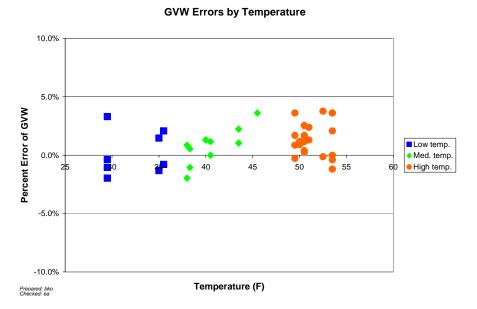


Figure 3-3 - Post-Validation GVW Percent Error vs. Temperature – 510100 – 04-Dec-2008

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the

drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. There is no apparent relationship between speed and axle spacing measurements.

0.20 0.15 Spacing error (ft) 0.00 Speed/space -0.05 -0.10 -0.15-0.20 Speed (mph)

Drive Tandem Spacing vs. WIM Speed

Figure 3-4 - Post-Validation Spacing vs. Speed - 510100 - 04-Dec-2008

3.1 Temperature-based Analysis

Prepared: bko Checked: ea

The three temperature groups were created by splitting the runs between those at 29 to 36 degrees Fahrenheit for Low temperature, 37 to 46 degrees Fahrenheit for Medium temperature and 47 to 54 degrees Fahrenheit for High temperature.

Table 3-2 - Post-Validation Results by Temperature Bin – 510100 – 04-Dec-2008

Element	95% Limit	Low Temperature 29 to 36 °F	Medium Temperature 37 to 46 °F	High Temperature 47 to 54 °F
Steering axles	<u>+</u> 20 %	$2.3 \pm 6.1\%$	$0.0 \pm 5.0\%$	$2.0 \pm 4.8\%$
Tandem axles	<u>+</u> 15 %	$0.1 \pm 6.4\%$	$1.3 \pm 6.2\%$	$1.6 \pm 5.7\%$
GVW	<u>+</u> 10 %	$0.2 \pm 4.4\%$	$0.8 \pm 3.3\%$	$1.4 \pm 3.0\%$
Axle spacing	+ 0.5 ft	$0.0 \pm 0.2 \text{ ft}$	0.0 ± 0.1 ft	0.0 ± 0.1 ft

Prepared: ea Checked: bko

As it can be seen in Table 3-2 the equipment overestimates all weights through the observed temperature range.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. From Figure 3-5 it can be seen that partial truck (diamonds) is overestimated throughout the temperature range. The golden truck (squares) shows a reasonable estimation with a slight overestimation as the temperature increases. Variability in error is greater at high temperature. The variability is associated more closely with the differences in truck responses than with actual temperature differences.

GVW Errors vs. Temperature by Truck

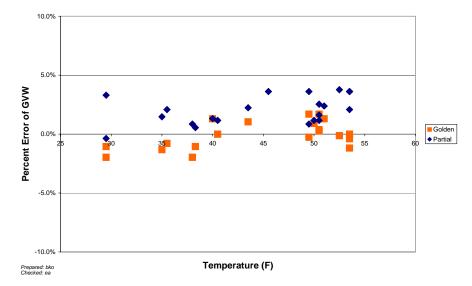


Figure 3-5 - Post-Validation GVW Percent Error vs. Temperature by Truck-510100-04-Dec-2008

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. As it can be seen in Figure 3-6, steering axle errors are generally overestimated. Variability in error is greater at low and high temperature.

page 8

Steering Axle Errors vs. Temperature

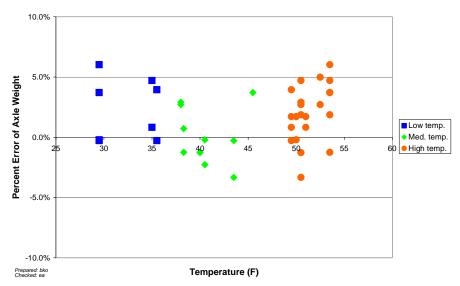


Figure 3-6 - Post-Validation Steering Axle Error vs. Temperature by Group – 510100 – 04-Dec-2008

3.2 Speed-based Analysis

The three speed groups were created using 52 to 57 mph for Low speed, 58 to 61 mph for Medium speed and 62+ mph for High speed.

Table 3-3 - Post-Validation Results by Speed Bin – 510100 – 04-Dec-2008

Element	95%	Low	Medium	High
	Limit	Speed	Speed	Speed
		52 to 57 mph	58 to 61 mph	62+ mph
Steering axles	<u>+</u> 20 %	$2.4 \pm 5.6\%$	$2.0 \pm 4.8\%$	$-0.3 \pm 3.5\%$
Tandem axles	<u>+</u> 15 %	$1.5 \pm 6.2\%$	$0.9 \pm 5.5\%$	$1.1 \pm 6.7\%$
GVW	<u>+</u> 10 %	$1.4 \pm 4.0\%$	$0.8 \pm 3.3\%$	$0.7 \pm 2.4\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: ea Checked: bko

From Table 3-3 it can be seen that the equipment overestimates all weights at all speeds with the exception of steering axle weights, which are underestimated on average at high speed.

From Figure 3-7 it can be seen that the partial truck (diamonds) is overestimated throughout the speed range. The golden truck (squares) is estimated with reasonable accuracy. Variability is greater at low and medium speed. There were no speed constraints on the trucks besides the grade of the site itself. The partial truck was not able to accelerate enough to reach the same high speeds as the golden truck.



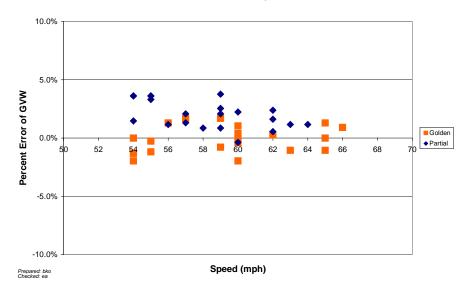


Figure 3-7 - Post-Validation GVW Percent Error vs. Speed by Truck-510100-04- Dec-2008

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9. Figure 3-8 the equipment generally overestimates steering axle errors but there is less bias as the speed increases.

Steering Axle Errors vs. Speed

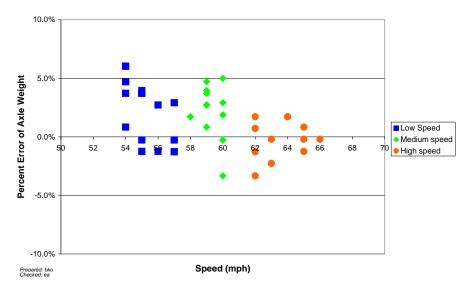


Figure 3-8 - Post-Validation Steering Axle Percent Error vs. Speed by Group $-\,510100-04\text{-Dec-}2008$

3.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is 2.0 percent. The misclassification is based on one truck (Class 6) identified as a bus (Class 4) by the WIM equipment.

Table 3-4 - Truck Misclassification Percentages for 510100 - 04-Dec-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	100	5	0	6	9
7	N/A				
8	0	9	0	10	N/A
11	N/A	12	N/A	13	0

Prepared: ea Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 - Truck Classification Mean Differences for 510100 - 04-Dec-2008

Class	Mean	Class	Mean	Class	Mean
	Difference		Difference		Difference
4	UNK	5	0	6	- 9
7	N/A				
8	0	9	0	10	N/A
11	N/A	12	N/A	13	0

Prepared: ea Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more

vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. Since the classification data met research quality standards, the observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 - Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: ea Checked: bko

4 Pavement Discussion

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

The WIM site is a section of pavement that is 305 meters long with the WIM scale located at 274.5 meters from the beginning of the test section. An ICC profiler was used to collect longitudinal profiles of the test section with a sampling interval of 25 millimeters.

Profile data collected at the SPS WIM location by Stantec Consultants on October 23, 2008 were processed through the LTPP SPS WIM Index software, version 1.1. This WIM scale is installed on a rigid pavement.

A total of 16 profiler passes were conducted over the WIM site. Since the issuance of the LTPP directive on collection of longitudinal profile data for SPS WIM sections, the requirements have been a minimum of 3 passes in the center of the lane and one shifted to each side. For this site the Regional Support Contractor has completed 9 passes at the center of the lane, 3 passes shifted to the left side of the lane, and 3 passes shifted to the right side of the lane. Shifts to the sides of the lanes were made such that data were

collected as close to the lane edges as was safely possible. For each profiler pass, profiles were recorded under the left wheel path (LWP) and the right wheel path (RWP).

The SPS WIM Index software, version 1.0 was developed with four different indices: LRI, SRI, Peak LRI and Peak SRI. The LRI incorporates the pavement profile starting 25.8 m prior to the scale and ending 3.2 m after the scale in the direction of travel. The SRI incorporates a shorter section of pavement profile beginning 2.74 m prior to the WIM scale and ending 0.46 m after the scale. The LRI and SRI are the index values for the actual location of the WIM scale. Peak LRI is the highest value of LRI, within 30 m prior to the scale. Peak SRI indicates the highest value of SRI that is located between 2.45 m prior to the scale and 1.5 m after the scale. Also, a range for each of the indices was developed to provide the smoothness criteria. The ranges are shown in Table 4-1. When all of the values are below the lower thresholds, it is presumed unlikely that pavement smoothness will significantly influence sensor output. When one or more values exceed an upper threshold there is a reasonable expectation that the pavement smoothness will influence the outcome of the validation. When all values are below the upper threshold but not all below the lower threshold, the pavement smoothness may or may not influence the validation outcome.

Table 4-1 - Thresholds for WIM Index Values

Index	Lower Threshold (m/km)	Upper Threshold (m/km)
LRI	0.50	2.1
SRI	0.50	2.1
Peak LRI	0.50	2.1
Peak SRI	0.75	2.9

Prepared: als Checked: jrn

Table 4-2 shows the computed index values for 11 profiler passes for this WIM site. Five consistent runs were selected from the nine provided for use in presentation of the results. The average values over the passes in each path were also calculated when three or more passes were completed. These are shown in the right most column of the table. Values above the upper index limits are presented in bold and values below the lower index limits are presented in italics.

page 13

Table 4-2 - WIM Index Values - 510100 -23-Oct-2008

Profile	r Passes	3	Pass 1	Pass 2	Pass 3	Pass 4	Pass 5	Ave.
Center	LWP	LRI (m/km)	0.800	0.729	0.815	0.699	0.748	0.758
		SRI (m/km)	0.695	0.492	0.786	0.503	0.593	0.614
		Peak LRI (m/km)	0.813	0.804	0.825	0.748	0.765	0.791
		Peak SRI (m/km)	0.737	0.812	0.826	0.708	0.777	0.772
	RWP	LRI (m/km)	0.844	0.931	0.993	0.837	0.853	0.892
		SRI (m/km)	0.622	0.778	0.756	0.547	0.666	0.674
		Peak LRI (m/km)	0.844	0.931	0.997	0.837	0.853	0.892
		Peak SRI (m/km)	0.865	1.129	0.964	0.791	0.873	0.924
Left	LWP	LRI (m/km)	1.092	1.045	0.918			1.018
Shift		SRI (m/km)	1.040	1.226	0.731			0.999
		Peak LRI (m/km)	1.110	1.067	0.996			1.058
		Peak SRI (m/km)	1.254	1.496	0.887			1.212
	RWP	LRI (m/km)	0.899	1.097	0.758			0.918
		SRI (m/km)	0.753	0.555	0.536			0.615
		Peak LRI (m/km)	0.899	1.103	0.872			0.958
		Peak SRI (m/km)	1.141	1.542	0.907			1.197
Right	LWP	LRI (m/km)	0.918	0.866	0.869			0.884
Shift		SRI (m/km)	0.950	1.019	1.015			0.995
		Peak LRI (m/km)	0.918	0.866	0.869			0.884
		Peak SRI (m/km)	1.234	1.211	1.226			1.224
	RWP	LRI (m/km)	0.891	0.835	0.845			0.857
		SRI (m/km)	0.739	0.885	0.461			0.695
		Peak LRI (m/km)	0.893	0.842	0.845			0.860
		Peak SRI (m/km)	0.915	1.056	0.865			0.945

Prepared: als Checked: jrn

From Table 4-2 it can be seen that three of the indices computed from the profiles are below the lower threshold values with the remainder of the indices falling between the upper and lower threshold values. These values indicate that the pavement roughness may or may not interfere with successful validation of the site. However, as the site was successfully validated no remediation recommendation is offered.

The profile data evaluated was collected after the site installation. There is no profile data available for prior visits.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement no distresses that would influence truck movement across the WIM scales were noted.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the

WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires and any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes bending plate sensors and iSINC electronics. The sensors are installed in a portland cement concrete pavement about 424 ft in length. The roadway outside this short section is asphalt.

On December 1, 2008, an SSM board and firmware was replaced and a remote calibration was performed using the front axle values. This resulted in a change in system parameters.

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors and system components were found to be within operating parameters.

5.2 Calibration Process

Upon our arrival at the site, we found the system parameters were not the same as we left them at the conclusion of our last validation on July 25, 2007. The sensors were remotely calibrated immediately prior to our arrival following equipment maintenance.

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs.

The operating system weight compensation parameters that were in place prior to the Pre-Validation are in Table 5-1.

Left Right Sensor 1 Sensor 2 Speed Bin 72 kph 3565 3565 88 kph 3565 3565 104 kph 3565 3565 121 kph 3565 3565 137 kph 3565 3565

Table 5-1 - Initial System Parameters - 510100 - 02-Dec-2008

Prepared: ea Checked: bko

5.2.1 Calibration Iteration 1

As a result of the Pre-Validation, where there was consistent overestimation throughout the speed range, the compensation factors were adjusted as shown in Table 5-2. All factors were adjusted the same amount as the difference between factors for the individual speed bins was very small.

Table 5-2 - Calibration Iteration 1 - Change in Parameters - 510100 - 03-Dec-2008

	Right		Left	
Speed Bins	Sensor 1	Change	Sensor 2	Change
72 kph	3422	-4.0%	3422	-4.0%
88 kph	3422	-4.0%	3422	-4.0%
104 kph	3422	-4.0%	3422	-4.0%
121 kph	3422	-4.0%	3422	-4.0%
137 kph	3422	-4.0%	3422	-4.0%

Prepared: ea

Checked: bko

Table 5-3 shows the results for the calibration validation passes. The reduction in overestimation was considered sufficient to terminate calibration of the lane.

Table 5-3 - Calibration Iteration 1 - Results - 510100 - 03-Dec-2008 (01:45 PM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.6 \pm 5.0\%$	Pass
Tandem axles	±15 percent	$1.9 \pm 4.7\%$	Pass
GVW	±10 percent	$1.4 \pm 1.5\%$	Pass
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: ea

Checked: bko

page 15

Figure 5-1 illustrates the GWV errors observed after calibration.

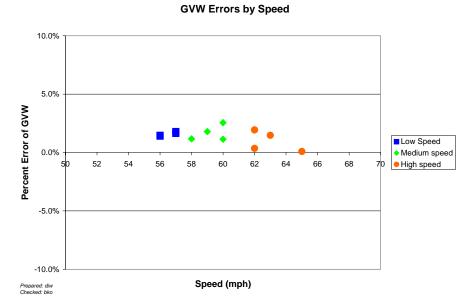


Figure 5-1 - Calibration Iteration 1 - GVW Percent Error vs. Speed Group - 510100 - 03-Dec-2008 (01:45 PM)

5.3 Summary of Traffic Sheet 16s

This site has validation information from previous visits as well as the current one in the tables below for this equipment installation. Table 5-4 has the information for

page 16

TRF_CALIBRATION_AVC for Sheet 16s submitted prior to this validation as well as the information for the current visit. The Sheet 16s available reflect only this contractor's validation visits.

Table 5-4 - Classification Validation History – 510100 – 04-Dec-2008

Date	Method	Mean Difference				Percent
		Class 9	Class 8	Other 1	Other 2	Unclassified
12/04/2008	Manual	0	0	CL 5: 0	CL 6: -9	0
12/02/2008	Manual	0	0	CL 5: 0	CL 6: 0	0
7/26/2007	Manual	0	0			0
7/24/2007	Manual	0	0			0
02/01/2007	Manual	0	0			0
01/30/2007	Manual	0	0			0

Prepared: ea Checked: bko

Table 5-5 has the information for TRF_CALIBRATION_WIM for Sheet 16s submitted prior to this validation as well as the information for the current visit for this equipment installation. The Sheet 16s available reflect only this contractor's validation visits.

Table 5-5 - Weight Validation History – 510100 – 04-Dec-2008

Date Method		Mean Error and (SD)			
		GVW	Single Axles	Tandem Axles	
12/03/2008	Test Trucks	1.0 (1.6)	1.5 (2.5)	1.2 (2.9)	
12/02/2008	Test Trucks	4.2 (1.3)	0.8 (2.3)	5.1 (2.9)	
7/26/2007	Test Trucks	0.1 (3.0)	-2.7 (5.1)	0.9 (4.5)	
7/24/2007	Test Trucks	-0.4 (3.1)	-0.5 (4.2)	0.4 (5.5)	
02/01/2007	Test Trucks	-0.8 (2.7)	-4.7 (2.6)	-0.1 (3.6)	
01/30/2007	Test Trucks	0.7 (2.7)	-2.6 (3.2)	1.3 (3.5)	

Prepared: ea Checked: bko

5.4 Projected Maintenance/Replacement Requirements

This site is scheduled for semi-annual maintenance under the installation contract.

It is recommended that the fastening nuts for both weigh pads be cleaned before winter and the silicon around them replaced. Figure 5-2 and Figure 5-3 illustrate show the some of the exposed nuts and the level of exposure to treatment chemicals for the frame fastenings in this lane.



Figure 5-2 - 510100 Example nut in leading WIM Sensor 2-Dec-2008



Figure 5-3 - 510100 Example nut in trailing WIM Sensor 2-Dec-2008

6 Pre-Validation Analysis

Upon our arrival at the site, we found the system parameters were not the same as we left them at the conclusion of our last validation on July 25, 2007. The sensors were remotely calibrated the day prior to our arrival following equipment maintenance.

The factors in place at the end of our last Validation visit and those found prior to validation are shown below.

Table 6-1 - Calibration Factor Change – 510100 – since 25-Jul-2007

	Left Se	ensors 1/3	Right S	Right Sensors 2/4	
	02-Dec-2008	25-Jul-2007	02-Dec-2008	25-Jul-2007	
72 kph	3565	3700	3565	3700	
88 kph	3565	3700	3565	3700	
104 kph	3565	3700	3565	3700	
121 kph	3565	3700	3565	3700	
137 kph	3565	3700	3565	3700	

Prepared: ea

Checked: bko

This pre-validation analysis is based on test runs conducted December 2, 2008 during the late morning and afternoon at test site 510100 on US 29. This SPS-1 site is at milepost 12.8 on the southbound, righthand lane of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 76,840 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 65,580 lbs., the "partial" truck.

For the initial validation each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 51 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 38 to 50 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-2.

As shown by Table 6-2 this site passed the weight and spacing precision requirements for research quality data. The degree of bias for GVW was considered large enough to merit calibration iteration although the front axle estimate (the statistic used for remote calibration) was essentially unbiased.

Table 6-2 - Pre-Validation Results – 510100 – 02-Dec-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$0.8 \pm 4.7\%$	Pass
Tandem axles	±15 percent	$5.1 \pm 5.7\%$	Pass
GVW	±10 percent	$4.2 \pm 2.7\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	0.0 ± 0.1 ft	Pass

Prepared: ea

Checked: bko

The test runs were conducted primarily from late morning to late afternoon hours, resulting in a very narrow range of pavement temperatures. The runs were conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and one temperature group. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs due to the limited temperature range.

The three speed groups were divided into 51 to 57 mph for Low speed, 58 to 62 mph for Medium speed and 63+ mph for High speed. The one temperature group between 38 to 50 degrees Fahrenheit was designated Medium temperature.

Frenancial dilw Frenancial dilw Frenheric for the first series of the first series o

Speed versus Temperature Combinations

Figure 6-1 - Pre-Validation Speed-Temperature Distribution – 510100 – 02-Dec-2008

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. It can be seen in Figure 6-2 that the equipment overestimates GVW errors at all speeds. Variability in error is similar throughout the entire speed range.

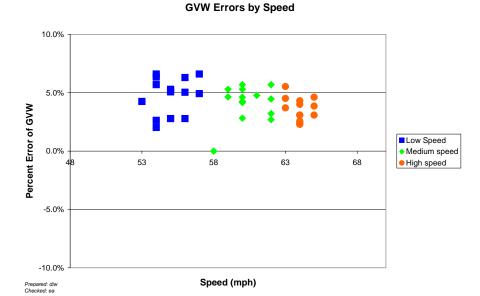


Figure 6-2 - Pre-Validation GVW Percent Error vs. Speed – 510100 – 02-Dec-2008

Figure 6-3 shows the relationship between temperature and GVW percentage error. Figure 6-3 shows that GVW errors are overestimated in the observed temperature range. Variability in error is consistent.

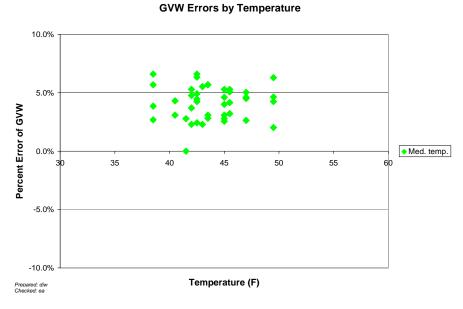


Figure 6-3 - Pre-Validation GVW Percent Error vs. Temperature – 510100 – 02-Dec-2008

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the

page 21

drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Figure 6-4 indicates that the errors in tandem spacing were not affected by changes in speed.

Drive Tandem Spacing vs. WIM Speed

0.20 0.15 0.10 0.00 48 53 58 63 68 Speed/space

Figure 6-4 - Pre-Validation Spacing vs. Speed - 510100 - 02-Dec-2008

6.1 Temperature-based Analysis

The one temperature group was between 38 to 50 degrees Fahrenheit and was labeled Medium temperature.

Table 6-3 - Pre-Validation Results by Temperature Bin – 510100 – 02-Dec-2008

Element	95% Limit	Medium Temperature 38 to 50 °F
Steering axles	<u>+</u> 20 %	$0.8 \pm 4.7\%$
Tandem axles	<u>+</u> 15 %	5.1 ± 5.7%
GVW	<u>+</u> 10 %	$4.2 \pm 2.7\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$

Prepared: ea Checked: bko

From Table 6-3 it is shown that the equipment produces an overestimation of all weights at this temperature range.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. Figure 6-5 shows the tendency of the equipment to overestimate GVW errors of both trucks. Variability in error is consistent throughout the temperature range.

GVW Errors vs. Temperature by Truck

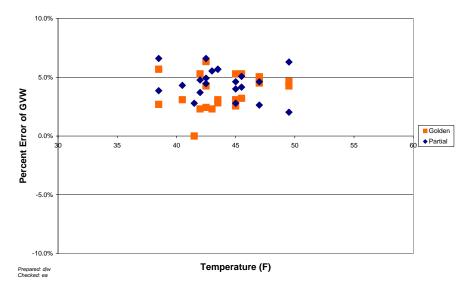


Figure 6-5 - Pre-Validation GVW Percent Error vs. Temperature by Truck - 510100 - 02-Dec-2008

Figure 6-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. It can been seen from Figure 6-6 that the equipment estimates steering axle errors with reasonable accuracy.

Steering Axle Errors vs. Temperature

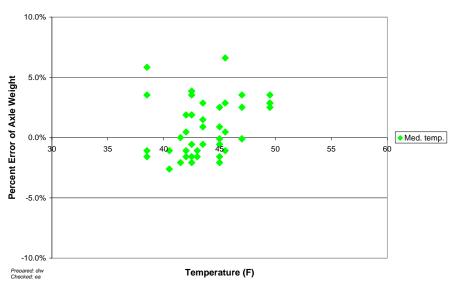


Figure 6-6 - Pre-Validation Steering Axle Error vs. Temperature by Group – 510100 – 02-Dec-2008

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -51 to 57 mph, Medium speed -58 to 62 mph and High speed -63+ mph.

Table 6-4 - Pre-Validation Results by Speed Bin – 510100 – 02-Dec-2008

Element	95% Limit	Low Speed 51 to 57 mph	Medium Speed 58 to 62 mph	High Speed 63+ mph
Steering axles	<u>+</u> 20 %	$2.3 \pm 4.5\%$	$1.0 \pm 5.2\%$	$-0.9 \pm 2.7\%$
Tandem axles	<u>+</u> 15 %	$5.3 \pm 4.8\%$	$5.3 \pm 6.5\%$	$4.6 \pm 6.3\%$
GVW	<u>+</u> 10 %	$4.7 \pm 3.4\%$	$4.4 \pm 2.2\%$	$3.5 \pm 2.2\%$
Axle spacing	<u>+</u> 0.5 ft	0.0 ± 0.1 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: ea Checked: bko

In Table 6-4 it is shown that the equipment produces an overestimation of all weights at all speeds with an exception of steering axles, which are underestimated at high speeds. Variability in error is similar throughout the speed range.

Figure 6-7 shows the tendency of the equipment to overestimate GVW for both trucks with a slight downward trend from low to high speeds. Variability in error is consistent throughout the speed range.

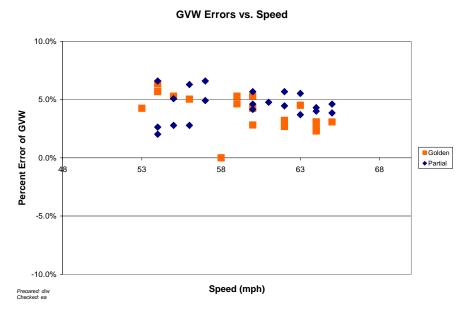


Figure 6-7 - Pre-Validation GVW Percent Error vs. Speed Group - 510100 -02-Dec-2008

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. It can be seen in Figure 6-8 that the equipment

mostly overestimates steering axle errors at all speeds with a downward trend from low to high speed. Variability in error is greater at low speeds when compared to high speeds.

Steering Axle Errors vs. Speed

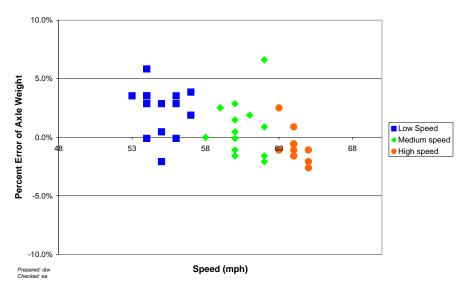


Figure 6-8 - Pre-Validation Steering Axle Percent Error vs. Speed Group - 510100 - 02-Dec-2008

6.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-5 has the classification error rates by class. The overall misclassification rate is zero percent.

Table 6-5 - Truck Misclassification Percentages for 510100 - 02-Dec-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

Prepared: ea

Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them a re matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-6 - Truck Classification Mean Differences for 510100 - 02-Dec-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

Prepared: ea Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. The observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-7 - Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: ea Checked: bko

page 26

6.5 Prior Validations

The last validation for this site was done July 25, 2007. It was the second validation of the site. The site was producing research quality data. Figure 6-9 shows the GVW Percent Error vs. Speed for the post validation runs. The site was validated with two trucks. The "Golden" truck was loaded to 74,610 lbs. The "partial" truck which had an air suspension tractor tandem and a 9 tapered steel leaf and a rocker bar suspension for the trailer axle. It was loaded to 64,880 lbs.

GVW Errors by Speed 10.0% 5.0% Percent Error of GVW Low Speed 0.0% Medium speed 52 62 64 66 68 High speed -5.0% -10.0% Speed (mph)

Figure 6-9 - Last Validation GVW Percent Error vs. Speed – 510100 – 25-Jul-2007

Table 6-8 shows the overall results from the last validation. Compared to the Pre-Validation results in Table 6-2 which shows an overestimation of all weights, Table 6-8 shows an underestimation for steering axles. The variability observed at the Pre-Validation was generally less than at the end of the last validation.

Table 6-8 - Last Validation Final Results – 510100 – 25-Jul-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$-2.7 \pm 10.3\%$	Pass
Tandem axles	±15 percent	$0.9 \pm 9.0\%$	Pass
GVW	±10 percent	$0.1 \pm 6.1\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.2 \text{ ft}$	Pass

Prepared: ea Checked: bko

Table 6-9 has the results at the end of the last validation by temperature. As the temperature ranges do not overlap comments on changes due to temperature are not appropriate. Through this validation the equipment has been observed at temperature from 27 to 96 degrees Fahrenheit.

Table 6-9 – Last Validation Results by Temperature Bin – 510100 – 25-Jul-2007

Element	95% Limit	Low Temperature 71-80 °F	Medium Temperature 81-89 °F	High Temperature 90-96 °F
Steering axles	<u>+</u> 20 %	$-4.8 \pm 11.5\%$	$-1.5 \pm 9.4\%$	$-1.5 \pm 12.0\%$
Tandem axles	<u>+</u> 15 %	$0.1 \pm 11.4\%$	$1.0 \pm 7.5\%$	$1.7 \pm 8.7\%$
GVW	<u>+</u> 10 %	$-1.0 \pm 8.1\%$	$0.5 \pm 5.7\%$	$0.9 \pm 4.4\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.4 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: ea Checked: bko

page 27

Table 6-10 has the results of the prior post validation by speed groups. As compared to the Pre-Validation, Table 6-10 shows an underestimation of all weights at low speed with larger variability.

Table 6-10 - Last Validation Results by Speed Bin – 510100 – 25-Jul-2007

Element	95% Limit	Low Speed	Medium Speed	High Speed
		53-56 mph	57-61 mph	62+ mph
Steering axles	<u>+</u> 20 %	$-7.0 \pm 11.8\%$	$0.6 \pm 5.8\%$	$-1.0 \pm 4.7\%$
Tandem axles	<u>+</u> 15 %	-0.1 ± 11.1%	$0.3 \pm 9.1\%$	$2.7 \pm 5.4\%$
GVW	<u>+</u> 10 %	$-1.6 \pm 6.1\%$	$0.0 \pm 6.5\%$	$2.2 \pm 4.1\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.5 \text{ ft}$

Prepared: ea Checked: bko

7 Data Availability and Quality

As of December 2, 2008 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site is shown in Table 7-1. It includes only data for this sensor installation since no validation data is available for previous installations. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. As can be seen from the table only 2007 has a sufficient quantity to be considered a complete year of data. In the absence of validation information for prior installations it can be seen that at least three additional years of research quality data are needed to meet

the goal of a minimum of 5 years of research weight data assuming that 210 days of data are received for 2008.

Table 7-1 - Amount of Traffic Data Available 510100 - 02-Dec-2008

Year	Classification Days	Months	Coverage	Weight Days	Months	Coverage
2007	325	12	Full Week	332	12	Full Week
2008	194	7	Full Week	194	7	Full Week

Prepared: ea

Thecked: bko

page 28

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 9s and Class 5s constitute more than 10 percent of the truck population. Based on the data collected following this validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-2 - GVW Characteristics of Major sub-groups of Trucks – 510100 – 04-Dec-2008

Characteristic	Class 9	Class 5
Percentage Overweights	0 %	0 %
Percentage Underweights	0 %	0 %
Unloaded Peak	32,000 lbs	
Loaded Peak	72,000 lbs	
Peak		12,000 lbs

Prepared: ea

Checked: bko

The expected percentage of unclassified vehicles is one percent. This is based on the percentage of unclassified vehicles in the Post-Validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-3. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation period.

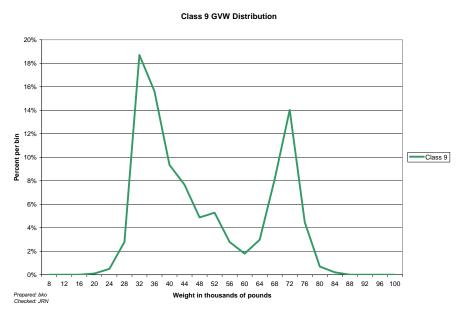


Figure 7-1 - Expected GVW Distribution Class 9 – 510100 – 04-Dec-2008

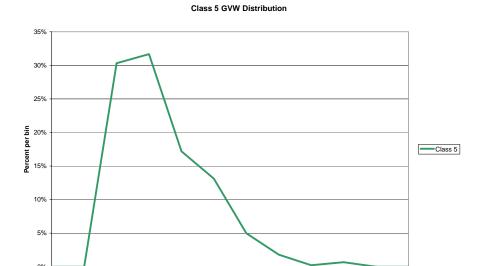


Figure 7-2 - Expected GVW Distribution Class 5 - 510100 - 04-Dec-2008

24

20

12

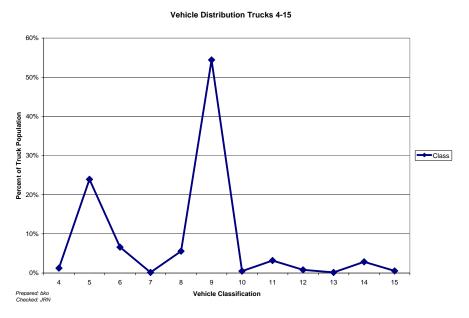


Figure 7-3 - Expected Vehicle Distribution - 510100 - 04-Dec-2008

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

```
Sheet 19 – Truck 1 – 3S2 loaded air suspension (4 pages)
Sheet 19 – Truck 2 – 3S2 partially loaded air suspension (4 pages)
Sheet 20 – Classification verification – Pre-Validation (2 pages)
Sheet 20 – Classification verification – Post-Validation (2 pages)
Sheet 21 – Pre-Validation (3 pages)
Sheet 21 – Calibration Iteration 1 – (1 page)
Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheet – (1 page)

Test Truck Photographs (6 pages)

LTPP Mod 3 Classification Scheme (1 page)

Final System Parameters (1 page)
```

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the Pre-Validation and Post-Validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: Virginia

SHRP ID: 510100

Additional Lane: 510199

1.	General Information	3
2.	Contact Information	3
	Agenda	
	Site Location/ Directions	
	Truck Route Information	
	Sheet 17 – Virginia (510100)	

Figures

Figure 4-1 – Sites 510100 and 510199 in Virginia	4
Figure 5-2 – Truck Route at 510100 and 510199 in Virginia	6
Figure 7-1 – Site Equipment Layout for 510100 and 510199 in Virginia	
Figure 7-2 – Site Map for 510100 and 510199 in Virginia	
Tigule 7.2 Site iviap for 510100 and 510199 in Virginia	10
Photos	
Photo 1 - 51_0100_Upstream_12_2_08.jpg	11
Photo 2 - 51_0100_Downstream_12_2_08.jpg	11
Photo 3 - 51_0199_Upstream_12_2_08.jpg	12
Photo 4 - 51_0199_Downstream_12_2_08.jpg	
Photo 5 - 51_0100_Power_Cabinet_12_2_08.jpg	13
Photo 6 - 51_0100_Power_Service_Meter_12_2_08.jpg	
Photo 7 - 51_0100_Telephone_Service_Drop_12_2_08.jpg	14
Photo 8 - 51_0100_Cabinet_Exterior_12_2_08.jpg	
Photo 9 - 51_0100_Cabinet_Interior_Front_12_2_08.jpg	
Photo 10 - 51_0100_Cabinet_Interior_Back_12_2_08.jpg	
Photo 11 - 51_0100_Leading_WIM_Sensor_12_2_08.jpg	
Photo 12 - 51_0100_Trailing_WIM_Sensor_12_2_08.jpg	
Photo 13 - 51_0199_Leading_WIM_Sensor_12_2_08.jpg	
Photo 14 - 51_0199_Trailing_WIM_Sensor_12_2_08.jpg	
Photo 15 - 51_0100_Leading_Loop_12_02_08.jpg	
Photo 16 - 51_0100_Trailing_Loop_12_2_08.jpg	
Photo 17 - 51_0199_Leading_Loop_ 12_02_08.jpg	
Photo 18 - 51_0199_Trailing_Loop_12_02_08.jpg	

MACTEC Ref. 642007022 2.119/2.120 12/12/2008 Page 3 of 19

Validation – VA 0100 w/auxiliary lane Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

1. General Information

SITE ID: 510100 and 510199

LOCATION: US-29 Bypass, milepost 12.8, near Danville

VISIT DATE: December 2, 2008

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Mohamed Elfino, 804-328-3173,

Mohamed.elfino@vdot.virginia.gov

Richard Bush, 804-786-7006,

Richard.bush@vdot.virginia.gov

Hamlin Williams, 804-786-0134,

Hamlin.williams@vdot.virginia.gov

FHWA COTR: Debbie Walker, 202-493-3068, <u>deborah.walker@fhwa.dot.gov</u>

FHWA Division Office Liaison: Lorenzo Casanova, 804-775-3362, Lorenzo.casanove@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: *No briefing requested for this visit.*

ON SITE PERIOD: Beginning December 2, 2008.

TRUCK ROUTE CHECK: Completed at Calibration.

4. Site Location/ Directions

NEAREST AIRPORT: Piedmont Triad International Airport, Greensboro, NC

DIRECTIONS TO THE SITE: US-29 Bypass, approximately 8 miles north of Danville.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: US-29 bypass, milepost 12.8; GPS = 36.6599° N,

-79.3656° W.

WIM SITE LOCATION MAP: See Figure 4.1



Figure 4-1 – Sites 510100 and 510199 in Virginia

5. Truck Route Information

ROUTE RESTRICTIONS: None

SCALE LOCATION: 9181 US-29, Blairs, VA; approximately 4 miles north of the site;

 $GPS = 36.7163^{\circ} N$, $-79.3793^{\circ} W$.

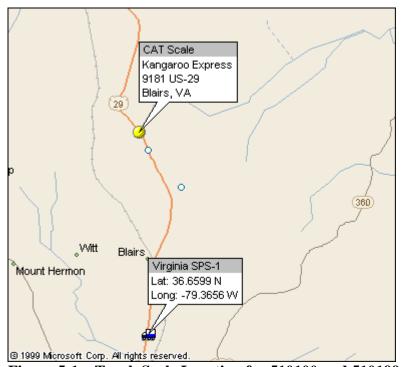


Figure 5-1 – Truck Scale Location for 510100 and 510199 in Virginia

TRUCK ROUTE: See Figure 5.2

NB on US-29 to Blairs/Danville exit (2.7 miles) SB on US-29 to Halifax exit (3.1 miles)

Total miles – 11.6 miles – 14 minutes

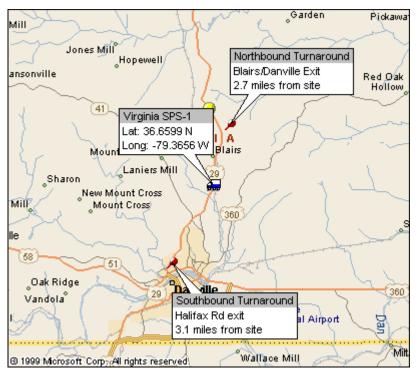


Figure 5-2 – Truck Route at 510100 and 510199 in Virginia

Validation – VA 0100 w/auxiliary lane Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

6. Sheet 17 – Virginia (510100)

1.* ROUTE <u>US-29 Bypass</u> MILEPOST <u>12.8</u> LTPP DIR	ECTION - N <u>S</u> E W
2.* WIM SITE DESCRIPTION - Grade Sag Nearest SPS section upstream of the site 5 1 0 1 0 4 Distance from sensor to nearest downstream SPS Section	
3.* LANE CONFIGURATION Lanes in LTPP direction2_ Lane width	_1_2_ ft
_	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Shoulder width1_1 ft	
4.* PAVEMENT TYPEPCC	
5.* PAVEMENT SURFACE CONDITION – Distress Survey Date: 12/2/2008 Filename:51_0100 Upstream 12_2_08.jg Date: 12/2/2008 Filename:51_0100 Downstream 12_2_0 Date: 12/2/2008 Filename:51_0199 Upstream 12_2_08.jg Date: 12/2/2008 Filename:51_0199 Downstream 12_2_0 6. * SENSOR SEQUENCELoop – Bending Plate – Bend 7. * REPLACEMENT AND/OR GRINDING// REPLACEMENT AND/OR GRINDING// REPLACEMENT AND/OR GRINDING// REPLACEMENT AND/OR GRINDING//	8.jpg 8.jpg 8.jpg ling Plate – Loop
8. RAMPS OR INTERSECTIONS Intersection/driveway within 300 m upstream of sensor loc distance Intersection/driveway within 300 m downstream of sensor distance Is shoulder routinely used for turns or passing? Y / N	
9. DRAINAGE (Bending plate and load cell systems only)	1 – Open to ground 2 – Pipe to culvert 3 – None
Clearance under plate 4 . 0 in Clearance/access to flush fines from under system Y / N	

10. * CABINET LOCATION Same side of road as LTPP lane \underline{Y} / N Median $\underline{Y} / \underline{N}$ Behind barrier \underline{Y} / N Distance from edge of traveled lane _2_7__ ft Distance from system 4 1 ft TYPE _____336 Short_____ CABINET ACCESS controlled by LTPP / STATE / JOINT ? Contact - name and phone number _Hamlin Williams __804-786-7006 ___ Alternate - name and phone number Roy Czinku 306-653-6627 11. * POWER Distance to cabinet from drop ____4 ___ ft Overhead / underground / solar / AC in cabinet? Service provider ______ Phone number _____ 12. * TELEPHONE Distance to cabinet from drop ____4 ___ ft Overhead / <u>under ground</u> / cell? Service provider _____ Phone Number ____ 13.* SYSTEM (software & version no.)- ___IRD iSINC_ Computer connection – RS232 / Parallel port / USB / Other 14. * TEST TRUCK TURNAROUND time __14 minutes__Distance _11.6__ mi. 15. PHOTOS **FILENAME** _51_0100_Power_Cabinet_12_2_08.jpg Power source _51_0100_Telephone_Service_Drop_10 28 08.jpg Phone source Cabinet exterior 51 0100 Cabinet Exterior 12 2 08.jpg Cabinet interior _51_0100_Cabinet_Interior_Back_12_2_08.jpg 51 0100 Cabinet Interior Front 12 2 08.jpg _51_0100_Leading_WIM_Sensor_12_2_08.jpg Weight sensors _51_0100_Trailing_WIM_Sensor_12_2_08.jpg 51 0199 Leading WIM Sensor 12 2 08.jpg 51_0199_Trailing_WIM_Sensor_12_2_08.jpg 51 0100 Leading Loop 12 2 08.jpg Other sensors _51_0100_Trailing_Loop_12_2_08.jpg _51_0199_Leading_Loop_12_2_08.jpg 51 0199 Trailing Loop 12 02 08.jpg Description Loop Sensors Downstream direction at sensors on LTPP lane: 51 0100 Downstream 12 2 08.jpg 51_0199_Downstream_12_2_08.jpg Upstream direction at sensors on LTPP lane: 51_0100_Upstream_12_2_08.jpg 51 0199 Upstream 12 2 08.jpg

COMMENTS		
concrete section = 425 feet		
leading edge of leading loop is 313 feet from approaching transition		
COMPLETED BY Dean J. Wolf		
PHONE <u>301-210-5105</u> DATE COMPLETED <u>12 / 2 / 2 0 0 8</u>		

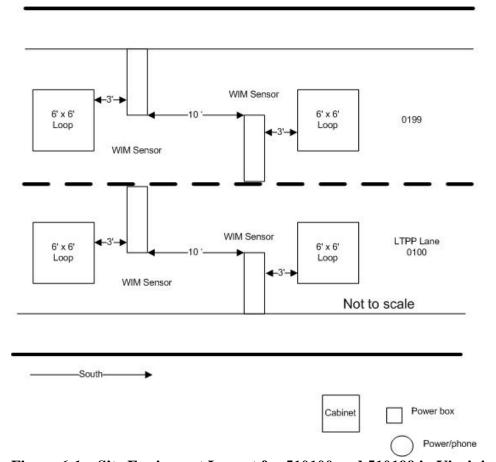


Figure 6-1 – Site Equipment Layout for 510100 and 510199 in Virginia

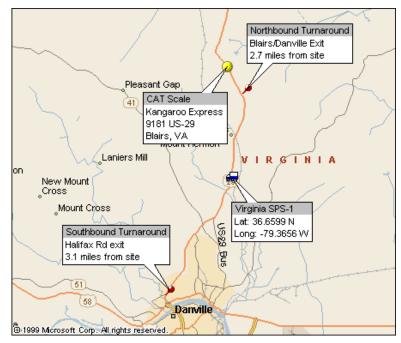


Figure 6-2 – Site Map for 510100 and 510199 in Virginia



Photo 1 - 51_0100_Upstream_12_2_08.jpg



Photo 2 - 51_0100_Downstream_12_2_08.jpg



Photo 3 - 51_0199_Upstream_12_2_08.jpg



Photo 4 - 51_0199_Downstream_12_2_08.jpg



Photo 5 - 51_0100_Power_Cabinet_12_2_08.jpg



Photo 6 - 51_0100_Power_Service_Meter_12_2_08.jpg



Photo 7 - 51_0100_Telephone_Service_Drop_12_2_08.jpg



Photo 8 - 51_0100_Cabinet_Exterior_12_2_08.jpg



Photo 9 - 51_0100_Cabinet_Interior_Front_12_2_08.jpg



Photo 10 - 51_0100_Cabinet_Interior_Back_12_2_08.jpg



Photo 11 - 51_0100_Leading_WIM_Sensor_12_2_08.jpg



Photo 12 - 51_0100_Trailing_WIM_Sensor_12_2_08.jpg



Photo 13 - 51_0199_Leading_WIM_Sensor_12_2_08.jpg



Photo 14 - 51_0199_Trailing_WIM_Sensor_12_2_08.jpg

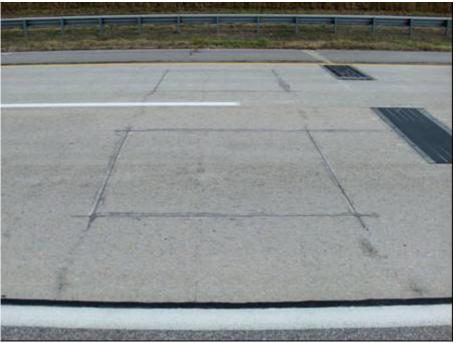


Photo 15 - 51_0100_Leading_Loop _12_02_08.jpg



Photo 16 - 51_0100_Trailing_Loop _12_2_08.jpg



Photo 17 - 51_0199_Leading_Loop_ 12_02_08.jpg



Photo 18 - 51_0199_Trailing_Loop_12_02_08.jpg

SHEET 18	STATE CODE	[51]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	12/2/2008

1.	DA	ATA PROCESSING –
	a.	Down load – State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review – State per LTPP guidelines State – Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	EC	QUIPMENT –
	a.	
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation _ Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control − State LTPP
	f.	Power − i. Type − ii. Payment − □ Overhead □ State □ Underground □ LTPP □ Solar □ N/A

SHEET 18	STATE CODE	[51]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	12/2/2008

	g.	Communication –
		i. Type − ii. Payment −
3.	PA	VEMENT –
	a.	Type – Nortland Concrete Cement Asphalt Concrete
	b.	Allowable rehabilitation activities – Always new Replacement as needed Grinding and maintenance as needed Maintenance only No remediation
	c.	Profiling Site Markings – Permanent Temporary
4.	ON a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required <u>2</u> ☐ days ☐ weeks
	b.	Notice for straightedge and grinding check4_
		ii. Accept grinding − State LTPP
	c.	Authorization to calibrate site – State only LTPP
	d.	Calibration Routine – LTPP – Semi-annually Annually Annually Annually Annually Annually Annually State per LTPP protocol – Semi-annually Annually State other –

SHEET 18	STATE CODE	[51]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	12/2/2008

	e.	Test V	Vehicles			
		i.	Trucks –			
			1st – <u>Air suspension 3S2</u>	☐ State	LTPP	⊠ LTPP
			2nd – <u>3S2 different weigh</u> 3rd –	State	State LTPP	LIPP
			4th –	State State		
		ii.	Loads –	State	LTPP	
		iii.	Drivers –	State	LTPP	
	f.	Contr	ractor(s) with prior successful expe	erience in WIM	I calibration in	n state:
	g.	Acces	ss to cabinet			
		i.	Personnel Access –			
			☐ State only			
			∑ Joint □ LTPP			
		ii.	Physical Access –			
		111.	Key			
			Combination			
	h.	State	personnel required on site –	⊠Yes □No)	
	i.	Traffi	ic Control Required –	☐Yes ⊠No)	
	j.	Enfor	rement Coordination Required –	☐Yes ⊠No)	
5.	SI	TE SPI	ECIFIC CONDITIONS –			
	a.	Funds	s and accountability –			
	b.	Repor	rts –			
	c.	Other	·			
	d.	Speci	al Conditions –			
	<u>.</u> .					
6.	CC	ONTAC	CTS –			
	a.	Equip	oment (operational status, access, o	etc.) –		
			Name: Roy Czinku	Phor	ne: <u>(306) 653-6</u>	<u>6627</u>
			Agency: <u>IRD</u>			

SHEET 18	STATE CODE	[51]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	12/2/2008

b.	Maintenance (equipment) – Name: Roy Czinku Agency: IRD	Phone:(306) 653-6627
c.	Data Processing and Pre-Visit Data – Name: <u>Roy Czinku</u> Agency: <u>IRD</u>	Phone:(306) 653-6627
d.	Construction schedule and verification – Name: <u>Don French</u> Agency: <u>Lynchburg District, VA D</u>	Phone: <u>(434) 947-6559</u> OOT
e.	Test Vehicles (trucks, loads, drivers) – Name: <u>Ed Foust</u> Agency: <u>Thompson Trucking, Inc.</u>	Phone: (434) 799-6743
f.	Traffic Control – Name: <u>Don French</u> Agency: <u>Lynchburg District, VA D</u>	Phone: <u>(434) 947-6559</u> P <u>OT</u>
g.	Enforcement Coordination – Name: Agency:	Phone:
h.	Nearest Static Scale Name: <u>Kangaroo Express</u> Location Phone:	:9181 US 29, Blairs, VA

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[51]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

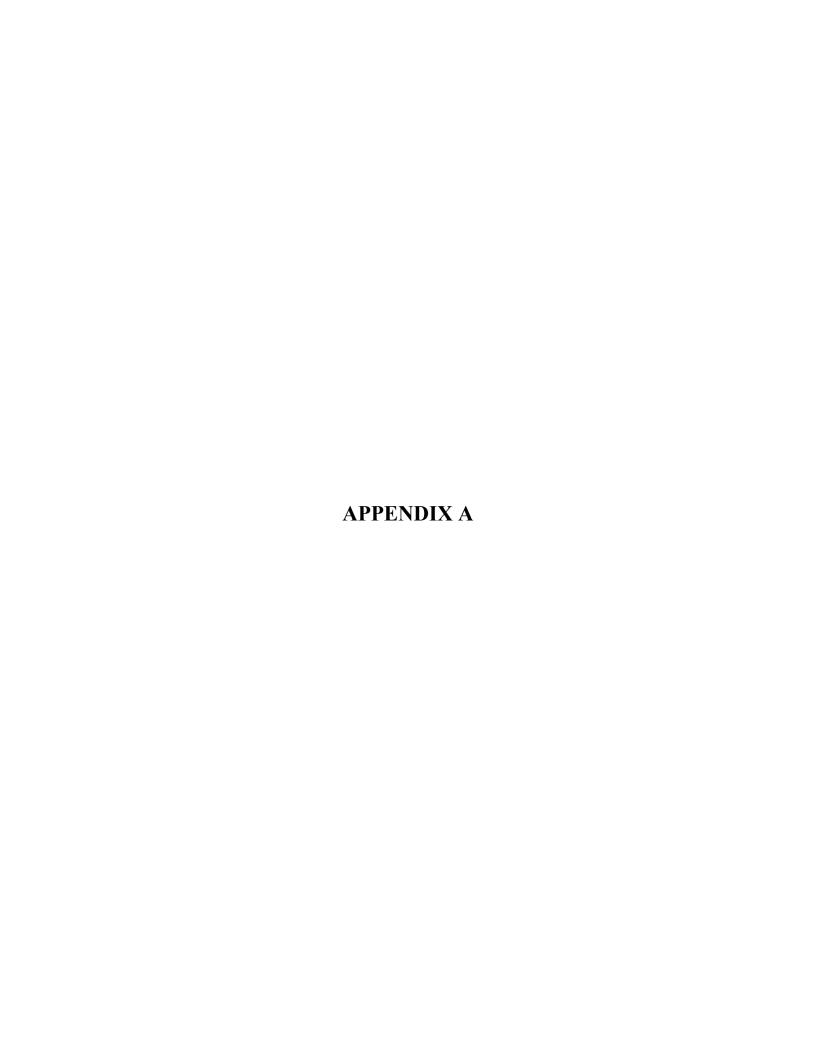
1. *	DATE OF CALIBRATION (MONTH/DAY/YEAR) [[12/2/2008]
2. *	TYPE OF EQUIPMENT CALIBRATED WIN	CLASSIFIER X BOTH
_ _ _	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
- - -	SENSORS INSTALLED IN LTPP LANE AT THIS SITE BARE ROUND PIEZO CERAMIC BAR CHANNELIZED ROUND PIEZO LOA CHANNELIZED FLAT PIEZO X IND OTHER (SPECIFY)	E (CHECK ALL THAT APPLY): RE FLAT PIEZO AD CELLS OUCTANCE LOOPS E (CHECK ALL THAT APPLY): B BENDING PLATES QUARTZ PIEZO CAPACITANCE PADS
5. E	QUIPMENT MANUFACTURERIRD/ PAT Traffic_	
	WIM SYSTEM CALIE	BRATION SPECIFICS**
6.**C	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE ((Y/N) <u>X</u> TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRESSE MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW 4.2 DYNAMIC AND STATIC SINGLE AXLES 0.8 DYNAMIC AND STATIC DOUBLE AXLES 5.1	,
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRA	ATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	556065
10.	CALIBRATION FACTOR (AT EXPECTED FREE FI	LOW SPEED)3565
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y. IF YES, LIST AND DEFINE AUTO-CALIBR	
	CLASSIFIER TE	EST SPECIFICS***
12.**	* METHOD FOR COLLECTING INDEPENDENT VOI VIDEOX_ MANUAL	
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 0 F	FHWA CLASS <u>5</u> <u>0</u> FHWA CLASS <u>6</u> <u>0</u> FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES:	FHWA CLASS
	SON LEADING CALIBRATION EFFORT:Dean J. W	
CO	NTACT INFORMATION: 301-210-5105	rev. November 9, 199

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[51]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR	R) [12/4/	2008]			
2.	* TYPE OF EQUIPMENT CALIBRATED	_WIM	CLAS	SSIFIER	<u>X</u> BO	тн
	* REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation		RESEARCHTRAININGNEW EQUIPM	IENT INSTA	LLATION	1
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS BARE ROUND PIEZO CERAMIC CHANNELIZED ROUND PIEZO CHANNELIZED FLAT PIEZO OTHER (SPECIFY)	_ BARE FL	AT PIEZO <u>X</u>	BENDING	G PLATES PIEZO 'ANCE PA	.DS
5.	EQUIPMENT MANUFACTURERIRD/ PAT To	raffic			_	
	WIM SYSTEM (CALIBRAT	ION SPECIFICS**			
6.**	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SC.	ALE (Y/N)	X TEST TRUCI	XS .		
	NUMBER OF TRUCKS COMPARED		2 NUMBER C	F TEST TRU	JCKS USE	ED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)		20_ PASSES PETRUCK TYPE 1	SUSPE	NSION	
7.	SUMMARY CALIBRATION RESULTS (EXPR MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	1.0 1.5	STANDARD DEVI	ATION2	. <u>6</u> . <u>5</u> . <u>9</u>	
8.	3 NUMBER OF SPEEDS AT WHICH CA	LIBRATIO	N WAS PERFORMED)		
9.	DEFINE THE SPEED RANGES USED (MPH)		55 60 65			_
10.	CALIBRATION FACTOR (AT EXPECTED FR	EEE FLOW	SPEED) <u>3422</u>			
11.*	* IS AUTO-CALIBRATION USED AT THIS SIT IF YES, LIST AND DEFINE AUTO-CA	` /				
	<u>CLASSIFII</u>	ER TEST SI	PECIFICS***			
12.*	** METHOD FOR COLLECTING INDEPENDENT VIDEOX_ MANUAL		E MEASUREMENT B PARALLEL C			
13.	METHOD TO DETERMINE LENGTH OF COU	JNT	TIME _ <u>X</u>	_ NUMBER	R OF TRUC	CKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEH *** FHWA CLASS 9 0 *** FHWA CLASS 8 0 *** PERCENT "UNCLASSIFIED" VEHICLES:	FHWA FHWA FHWA		<u>0</u> 	<u> </u>	
	RSON LEADING CALIBRATION EFFORT:	n J. Wolf, M	[ACTEC			
CC	ONTACT INFORMATION: 301-210-5105			rev. l	November	9, 1999



LTPP Traffic Data	* SPS PROJECT ID ;	0100 / 0199
*CALIBRATION TEST TRUCK #_1	* DATE 12/08	
PART I.		
1.* FHWA Class 2.* Number of Axle	s Number of	weight days <u> </u>
AXLES - units - (lbs) 100s lbs / kg		
GEOMETRY		
8 a) * Tractor Cab Style - Cab Over Engine Convention	b) * Sleeper Cab?	Y(N)
9. a) * Make: TNTGNAMED) * Model:	an franse	. Company of the second se
9. a) * Make: 57 (03)	desert .	
10.* Trailer Load Distribution Description:		
GRAVEL LAFDED OVEN	Trailer	
11. a) Tractor Tare Weight (units):	***************************************	
b). Trailer Tare Weight (units):		
12.* Axle Spacing – units m / feet and inches / fee	at and tantha	
. •		
A to B 15.0 B to C 4.4	C to D $\frac{21.6}{}$	
DtoE 4,4	E to F	
Wheelbase (measured A to last)	Computed 19.4	
13. *Kingpin Offset From Axle B (units)		
	to the rear)	
SUSPENSION		
	on (leaf, air, no. of leaves, taper	or flat leaf, etc.)
A 11R22-5 2 Pur		
		·
Et com on a financial and a fi		
F		

Sheet 19

6420070022_SPSWIM_TO_15_51_2.119_0100_Sheet_19_axle_scales_truck_1

51

* STATE_CODE

Sheet 19	* STATE_CODE	51
LTPP Traffic Data	* SPS PROJECT ID	0100 / 0199
*CALIBRATION TEST TRUCK #_2_	* DATE	12/2/08
72 00/01/04		

PART II

Day 1

*b) Average Pre-Test Loaded weight

*c) Post Test Loaded Weight

*d) Difference Post Test – Pre-test

77130

76540

- 5 9 O

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	9980	15790	15790	17780	17780		77120
2	9880	15880	12680	17750	17750		77140 -
3							
Average	9930	15835	15635	17765	17765		77130

Table 6. Raw data – Axle scales –

ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	9560	15770	15770	17710	17710		76520
2	9600	15760	15760	17720	17720		76560.
3							
Average	9580	15765	15765	(7715	17715		76540

Measured By	A. al	Verified By	EA.	Weight date _	12/2/1	08
	. 4 3/2 3/ (/ 440					

		Sheet 19		* !	STATE_CODE		51	
	L	TPP Traffic Data	ì		* SPS PROJECT ID		0100 / 0199	
	*CALIBRA	TION TEST TR	UCK # <u>1</u>	*]	DATE		12/3/00	
Rev. 08/31/0	1						·	
				Day 2				
7.2	*c) Post Te	e Pre-Test Loast Loaded We	ight	776430 - 600	•			
Table 5.2.	Raw data – Ax	xle scales – pr	e-test Axle C	Axle D	Axle E	Axle F	GVW	
1	0.000	15750	(5750	17770	(7770		77040	
2	9900	15850	15850	ma	(7710		77020	
3								
Average	9950	15800	15800	וחאט	17740		77030	
	· ··							
Table 6.2. l	Raw data – Ax	de scales –			,,	····	······	
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
	<u> </u>]					

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
2							
3							
Average							

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
- Frank	<u> </u>	15710	15710	(17770	\7720		76440	
2	9560	15710	15710	17720	17720		76420	. app
3								
Average	9570	15710	15710	17720	17720		76430	

Measured By	Verified By	4A.	Weight date	12/	3	08
	· -		-	- · · · · · · · · · · · · · · · · · · ·		

		Sheet 19			TATE_CODE		51	
		ΓΡΡ Traffic Data	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		PS PROJECT II)	0100 / 0199	
Rev. 08/31/0	······································	ΓΙΟΝ TEST TR	.UCK #_1_	* 1	DATE		12/4/08	
.01. 00/31/0	•		Day 3					
73	*c) Post Tes	e Pre-Test Los st Loaded We nce Post Test	ight	7691 763 -64				
Table 5.3.	Raw data – Ax	tle scales – pr	e-test					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
	9920	15%10	15010	17720	(7720		76930	
	9900	15%10	15810	17710	17710		76940	
Average	9910	15310	15810	17715	(7715		76960	
`able 6.3. I	Raw data – Ax	le scales –						
'ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
		,						
verage								
able 7.3. I	Raw data – Ax	le scales – po	st-test					
'ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
	9440	15780	15780	17670	17670		76340	

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	9440	15780	15780	17670	17670		76340
2	9560	15650	15650	17720	17720		76300
3							
Average	9500	15715	15715	17495	17695		76320

Measured By	Verified By	Typ.	Weight date 12	4/28
-------------	-------------	------	----------------	------

	*CALIBRAT	ION TEST TRUCK #_2_	* DATE	12/2/08	
Rev. 08/					
PART :	I.				
1.* FH	WA Class	2.* Number of A	Axles <u> </u>	Number of	weight days <u>3</u>
AXLE	\mathbf{S} - units -($\widehat{\mathbf{lbs}}$ / $\widehat{\mathbf{los}}$	00s lbs / kg			
GEOM	IETRY				
		Cab Over Engine / Conve	a set of the second control of the secon	Sleeper Cab?	Y(N)
9. a) * I	Make: [744]	(ローピーン b) * Model:			
10.* Tr	railer Load Distribu	ution Description:	one trave	n.	
					······································
b). 7	Trailer Tare Weigh	t (units): t (units): m / feet and inches /	feet and tenths	215	
A to B		B to C 4.2		gar F. 4.	
		D to E			
	Wheelbase (measu	red A to last)	Computed	44.1	
13. *Ki:	ngpin Offset From	Axle B (units)	+ is to the rear))	
SUSPE	NSION				
Axle A B C	14. Tire Size (1 F 22.5 11 R 22.5 11 R 22.5 11 R 22.5	15.* Suspension Description De	San Grand Profes	. of leaves, taper	
E	<u>112 24,5</u>	AIR			
F					

* STATE_CODE

* SPS PROJECT ID

5 I

0100/0199

Sheet 19

LTPP Traffic Data

 $6420070022_SPSWIM_TO_15_51_2.119_0100_Sheet_19_axle_scales_truck_2$

		Sheet 19		* S	TATE_CODE		51
	L'	TPP Traffic Dat	a		PS PROJECT ID)	0100 / 0199
		TION TEST TF	RUCK #_ 2] * [DATE		12/2/08
Rev. 08/31/0	1						
PART II							
				Day 1			
	*b) Average	e Pre-Test Lo	aded weight	659	zo		
		st Loaded We	•	652			
		nce Post Test	_	- 69	0		
Table 5. Ra	aw data – Axle	e scales – pre	-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	19280	11020	// OS Q	16800	16800		66920 ~
2	10280	11030	1(030	16790	16790		V5920 .
3							
Average	10280	11025	(1025	16795	16795		65923
l'able 6. Ra	<u>ıw data – Axle</u>	e scales –					· · · · · · · · · · · · · · · · · · ·
`\ss	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
2		1		1			

\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
I	9900	10970	10970	16690	16690		45270 1
2	9980	10920	10920	16710	(6710		65240 -
3							
Average	9940	10945	10945	16700	16700		65230

Measured By	<u> Jiw</u>	Verified By	<u> </u>	Weight date	12/2	108
	¥				(/	/

		Sheet 19		* S'	* STATE_CODE 51			
		ΓΡΡ Traffic Data			* SPS PROJECT ID 0100 / 01			
		TION TEST TR	UCK #_2_	* D	ATE		12/3/08	
Rev. 08/31/01								
				Day 2				
7.2	_	e Pre-Test Lo	_	65610				
	•	st Loaded We	_		25040			
	*d) Differer	nce Post Test	– Pre-test	_ 57:	<u> </u>			
Гable 5.2. F	Caw data – A	de scales – pr	e-test			1		
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
1	10550	10990	10990	16700	(6700		65600	
2	10200	llolo	1010	16700	(6700		65620	
3								
Average	12510	11000	000)/	(670)	16700		65610	
Гable 6.2. R	taw data – Ax	de scales –						

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
2							
3							
Average							

Table 7.2 Raw data – Axle scales – post-test

			D. 14D.				,
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	9880	16880	08801	cordl	16700		65040 -
2	9880	10880	108801	16700	16700		65040 2
3							
Average	9880	10880	0880J	16700	16700		65040

Measured By	Verified By	EA.	Weight date	12/3/08
111200001120 2)	, , , , , , , , , , , , , , , , , , , ,		Troigin date	

Sheet 19	* STATE_CODE	51
LTPP Traffic Data	* SPS PROJECT ID	0100 / 0199
*CALIBRATION TEST TRUCK #_2_	* DATE	12/4/08
*CALIBRATION TEST TRUCK #_2_	* DATE	12/1

*b) Average Pre-Test Loaded weight 7..3 *c) Post Test Loaded Weight *d) Difference Post Test – Pre-test

Table 5.3. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1.	10280	11040	11040	16670	16670		65700
2	10300	11060	11060	1660	16660		65740
3							
Average	/o.z.d0	11050	11050	16665	16665		65720

Table 6.3. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	i
2								
3								
Average								

Table 7.3. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
. Proc.	9940	10920	10920	16670	16670		65120
2	10000	10860	10860	167690	16690		65100 1
3							
Average	9970	10590	10890	16680	16680		65110

Measured By Verified By Weight date 12/4/08

Sheet 20	* STATE_CODE 51
LTPP Traffic Data	*SPS PROJECT_ID 0 1 0 0
Speed and Classification Checks * / of* 2	*DATE <u>/2/62/2008</u>

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
61	9	3764	61	<i>5</i> 3	70	6	3847	69	6
62	9	3705	64	9	65	9	3851	64	9
53	9 mg	333	534	85 0	60	6	3854	60	le
60	49	333	4258	8 9	43	9	3857	62	9
63	9	3230	63	9	50	6	38 <i>9</i> 7	52	6
66	6	373)	66	6	66	9	3911	67	9
60	9	3737	las l	.9	61	11	3 915	61	//
63	5	3740	61	5	64	9	3918	64	9
52	5	3フペ5	52	Ly.	(and a second	9	3921	Guf	9
65	9	3751	65	<u></u>	59	5	3924	59	5
65	9	3755	6 S	3	64	9	3928	63	9
64	9	3756	64	9	54	9	3247	5 3	9
62	8	3757	63	8	61	8	3 95 8	61	8
<u>(</u> S	8	3758	65	8	62	9	3968	62	
60		3743	66	9	56	E.F.	3970	SS	9
50	2	3764	59	9	66	5	3571	A	5
61	9	3765	63	9	64	9	3976	64	9
63	9	3769	62	S	65	9	39 77	64	9
وسيدين المساخل	9	3771	56	9	63	9	3985	Co Den	9
68	9	3778	67	9	66	9	<i>398</i> 8	66	9
60	9	3783	60	9	CS	9	3,550	70	9
59	9	3786	<i>5</i> 8	9	64	9	4020	6 Im	9
66	9	3824	GH	Sin'ny Lor	67	6.	4023	68	6
(3	9	3842	62	9	62-	€.	4035	60	8
65	Ça	3846	59	B 6	54	9	4637	53	Ĵ



Sheet 20	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
Speed and Classification Checks * 🕕 of* 者	* DATE	1210212003

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
64	9	4047	62	See Mary	63	9	4198	63	9
64	9	4042	62	9	つめ	5	4200	76	5
68	8	4058	67	8	60	9	4211	59	9
63	9	4061	61	9	67	9	4214	66	9
63	99	4125	50	# 9	60	9	4216	61	9
62	6	4126	62	6	66	9	4224	66	9
64	9	4147	62	Ŋ	65	9	4251	5866	Ŧ
60	Paris .	4150	60	Ö	(e)	٩	4228	60	9
62	9	4151	62	9	45	9	4272	W 5	9
65	8	4152	6 5	9	65	5	4275	4 5	5
62	9	4153	62	9	4 5	5	4279	4 3	,
65	9	4155	65	Name of Street, Street	53	5	4209	52.	<u> </u>
67	C	4159	67	8	<i>\\</i> 42	9	4294	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	7
ラフ	6	4161	5つ	Č.	(, (9	4297	59	C.
65	9	4163	64	9	62	প	4298	61	d
62	6	4166	62	6	62	\$6	4301	62	(
Car In	9	4168	61	9	64	q	4303	64	9
GI	6	4174	61	6	65	q	4308	65	9
65	9	4178	65	S	61	9	4325	6	9
62	6	4184	60	6	60	9	4357	58	474
602	6	4185	64	6	by	9	4329	(ed	q
60	9	4187	61	9	71.	4	4335	12	4
ナケ	9	4188		9	69	6	4336	69	(,
(7)	9	4193	67	Carlotte Car	65	5	43 54	63	()
67	9	4157	65	9	5 A	5	4354	5%	5

Recorded by MAPK 3

Direction S Lane / Time from 1236 to 1346



Sheet 20	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
Speed and Classification Checks * of*	* DATE	1210412008

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
6 262	# 9	12459	100	多ダ	48	8	12656	47	8
59	6	12465	59	6	57	8	12611	55	8
68	5	12482	<i>G</i> 8	5	69	9	12616	64	9
65	8	12517	64	8	64	9	12617	63	9
48	5	125)9	48	5	64	9	126.52	62	g
67	8	12528	65	8	bolo	4	12650	65	6
59	9	12523	58	9	58	9	12654	58	9
67	3	12527	66	9	60	9	12662	53	g
61	ture de la constitución de la co	12533	60	5	60	9	12671	\$ 60	\$ 9
52	5	12535	49	Energy management	67	5	12673	67	
6)	9	12540	61	9,2		6	13674	- 53	<u> </u>
56	9	12,542	5 5	9	<u>45</u>	6	12675	63	6
64	Ga	12545	63	6	65	8	12680	65	8
65	9	12547	64	9	62		12492	CY	9
66	9	12552	65	2	C+	5	12696	45	5
65	9	12553	65	Ÿ	62	9	12699	61	9"
59	Comp	12576	5 59	45	64	9	12702	62	9
60	9	12579	60	9	6	500	12703	67	Ĵ
60	6	12581	59	6	60	2	12704	59	9
54	57	12-587	55	5	55	8	12719	54	8
524	9	12-588	53	9	60	9	12-72-7	60	9
65	9	1259	65	9	60	9	12740	59	9
66	9	12597	65	9	50	5	12746	56	5
58	9	12599	60	9	62	9	12762	60	9
62	9	12602	6-	9	48	45	12767	48	

Recorded by MAPK

Direction S Lane / Time from \$18 Am to 9:22 Am 8:18 Am



Sheet 20	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
Speed and Classification Checks * of*	* DATE / 2/0	4/2008

WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
64	6	12772	64	6	52	9	12885	52_	9
4)	13	12775	34	13	61	6	12.888	61	6
40	9	12776	38	9	66	lo	12890	66	6
37	5	12778	35	5	67	6	12893	67	lies
69	9	12780	68	9	61	9	12899	59	.9
66	9	12782	65	9	62	9	12907	6)	9
55	9	12783		9	6 l	Č.	12908	59	6
63	9	12784	61	9	65	9	12915	65	9
65	9	12785	GM	9"	69	9	\$ 06	69	9
54	5	12787	53	5	73	5	09	73	5
69	5	12788	48	5	フ。	9	15	~ &	9
64	9	12790	63	9	54	9	17	53	9
66	8	12797	66	9 8	65	9	19	65	9
68	5	12099	66	9	65	9	34	62	9
65	9	12803	64	9	62	9	39	62	9
64	9	12804	62	9	55	9	44	د الم	9
64	9	12806	(2	9	61	9	23	59	9
64	9	12830	64	9	65	9	63	64	9
67	9	12837	67	9	64	9	67	62	9
67	5	12838	6.00	Lauren .	65	· g	69	65	.9
5)_	5	12857	5 2	5	57	5	76	56	9 5
フロ	5	12863	69	5	وريا	9	94	55	93
63	9	12870	63	G.	62		8.8	61	9
68	9	12875	60	9	65	9	90	64	9
65	€	12877	G5	8	(5	9	91	64	9

Recorded by MARK 2

Direction S Lane 1 Time from 9:22 to 1020 Am

Subel 21	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
WIM System Test Truck Records / of 5	* DATE	2001/201歩/

Rev. 08/31/2001

E.F space																
D-E space	<u>ي</u> ښ	3	3 (V)	3	3	" information	j Ž	フ. さ	7	3	3	3	3	3	(N)	M +
C-D space	9	09 A	0. N	100	0.7		0 7	7 7	ã	3	100	7.6	83	7 7	7	21.6
B-C space	3	3	J	きょ	9	t g	23	ナ	No.	かせ	7	ナデ	り さ	J F	2	でも
A-B space	之	0.0	9	N.	2	2	3	50	いき	シュ	ジュ	ří O	いど	0.17	10 J	14.9
<u></u>	0.3	<u>を</u> ゾ	3	20 U.	000	Ri	Ci	* &	6.33	Ŕ	J:83	M &	9	C &	70	8
Axle F weight																
Axle E weight.	200	TY/W	100	2/2 2/2	180	200	12/2	38	1880	158 158		8/6.a	\$\$ \$\$	20/2 King	7	36/36
Axle D weight.	76/2	77	3	and B	12 Sept 20 12 12 12 12 12 12 12 12 12 12 12 12 12	ÉY.	86/2	18	120	19/38	38/80	E 9/62	B	N. S.	21/20	83/2°
Axle C weight.	3/2	73 By	(9/6	Jel 1	19/25	5	7/1/2	2000	5/58	23/82	19/55	Hali	27	16/	35/65	76/92
Axie B weight.		Rail	77/25	7862	16 2/19	i Organia	9/65	Elge	27/16	63/6	17/95	TANK TANK	N Co	48/2	2/2	To the
Axle A weight.	Se S	47	Ž V	492	2/2	4	51/53	E9/CH	25/2	<u>N</u> 500	25	HEA.	15 S	NT/LH	15 A	482
Speed	Ü,	立	R	か	B	9	2	65	Ĭ,	ß	.0	6	さか	er ^e) S	K	8
No.	222	22	3257	73603	365]	ESE	5783	6305	eas	Sign	6228	3863	n B	3937	7007	5
<u>2</u>	1800		8:0	5.0	1:5286	3	132	221	A 18 parters		7		3.00	[252]	03	12:0
Pass	, recommendate to the second	, of the second section of the section of the second section of the second section of the section of the second section of the secti	<u></u>	Cp	8	\sim	Ţ,	H	N	V)	Q	9			Ø	00
<u>Ş</u>	~	5	CS	, ментический,	<i>₼</i>	And the state of t	H	7~*******	CR	, www.	H	est total bases and top	C	- platent de la Section de la	C	Volumenterphism
Radar Speed	E	īŋ	Ğ	B	ß	S	太	<i>S</i>	お	53	20	,	5	R	Ž,	25
Fvmit temp	<i>と</i> る い	38.0	5	ま が	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	in in	1 51 N	12 N	なられて	5.65	4	S	F	Ð	\$	ħ

Checked by __

Recorded by NHZK Z

ere en e				E-F space													
		8		D-E space	(M)	4.3	9 E	<i>J</i>		ä	34	3	Ţ	4.7	艺步	9	23
51	0100	2000		C-D space	200	5,0	0.7	21.6		0 7	2).6	i i	2,5	ا ا ا	27	0 7	<u>y</u>
		7	i i	B-C space	4.2	ナゴ	n t	- June	1	er,	J.	N.	7	5		i	J.
		121		A-B space	じた	15.0	7.5	15.0	424	Cestores The Control	<u>0</u>	3: 2	J.		000	なものさ	3
ODE	CT_ID			GVW	68.3	79.53	£ 5.00	800 150	45%	5	200	3. I. C. 89	1884	Z Ž	77.00	7.87	R.
* STATE_CODE	*SPS PROJECT	* DATE		Axle F weight													
* ST	*SP	~D~		Axle E weight.	80	Sell Sell	2002	N. S.		88/88	30	700	18/2	25/2	18 N 3	72.82	187
				Axle D weight.	10	27/2	To the second	15 15 15 15 15 15 15 15 15 15 15 15 15 1	Sty/troit	600		18	100 100	N.	194/86		28/
				Axle C weight.	586	196	N. N. S. T.		0.1% or	85/55	78	17/2	4	S. C.	John John	20	W.
	į	~ C		Axle B weight.	59/2	75/4	72			07/65	N.T.	3/45/4	The state of the s	564	13/8	375) hay
	i	2_of_		Axle A weight.	5/30	1.8L	20	462	N. W.	Soluq	W.	J. S. C.	En t,	12 12 00 00 00 00 00 00 00 00 00 00 00 00 00	42 July 1	S/S	J. C.
	c Data	cords		WIM Speed	E	C.L.	んり	55		3	49	To Contract of the Contract of	29	2	59	to	t
Sheet 2	LTPP Traffic Data	Fruck Re		Record No.	4000	335	25	431	4322	4323	BANA	RE	4537	£5.£0	404	4605	さらた
	LT	WIM System Test Truck Records		Time	1232 4262	1232 18CF	2:04:2	1214 (42)			13.55 HYB	13:55 HTD	3	14.1045E	433464	14.34 (20)	#:3) t(3)
		VIM Syst		Pass	8	157	0	0	Square S	galeringenden ,galeringe	ğ	Es.	14	Ţ	, pu	的	Po
	***************************************	jamente.		Truck	CY	**************************************	a	or designating to	N.	M	appendental services	C 6	**************************************	N	**************************************		nistrici annige
			/31/2001	Radar Speed	28	62	() Pro-	X	4	55	5	S	59	Į,	0	5	6
			Rev. 08/31/2001	Pvmt temp	ig V	a S	ħ,	44	\$	<u>5</u>	2	5	%	25.50	54	N.	3
<u> </u>	1			L	. 				K E				J	<u> </u>	I	1	l

6420070022_SPSWIM_TO_15_51_2.119_0100_pre-Validation_sheet_21

子子

<u>で</u>る

J

78.2 15.6

75

S T

かか

7 4

20

EN 26/18 37/25 51/0 05/25

0

14:50 40%

Ø

<4

6

2

63

7.7

2

いき

3

2/5 5/2 5/5 15/6 1/35

To

E : 51 (1) 23

B

4

9

135

N

Recorded by MAPK

Checked by_

2/18 848 266 16/1 VS/74

To

14:5 473

B

5000

Sheet 21	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
ystem Test True	* DATE	1210212008

Rev. 08/31/2001

E-F space														
D-E space	T	23	2	2,	S S	₩ 3-	77	M	3	3				- Laure Communication of the C
C-D space	27.6	0,	7.0	3	2.6	7	0.7	0.	216	7.50				777777000
B-C space	-	3	3	J.	ナ	3	r		-j-	t t				
A-B space	5.0	84 941 989	15.0	L?	15.0 0,0	877 4.6 4.3	10 0	8.5/145/4.3	78.6 15.0 4.4	E.7 5.7 0.89				
M/S	78.8	9.89	Š	88 83	S.	CÉ	78.7 15.0	13 13 13	28.C	() (b)				
Axle F weight			,	7,000										4
Axle E weight.	0.0	192	7.57	8 183	85/8.	26/30	00/20	197	82/38	78/91				ŝ
Axle D weight.	85/10:0//6:0	18%	183	81/9U	84 1 3/6 I	8455/6	86/28	54/2 57/2 84/2 79/2	20/5/2/2/2/2/2/2/2/2/2/2/2/2/2/2/2/2/2/2	12/3 78/91				
Axle C weight.					光	365	767	73/62	2 Has	13/2				l by
Axle B weight.	78/4 (8/30	79/20		58/2	200	59Kg 79Kg	38/82	34/13	7/24	13/1/25				Checked by
Axle A weight.	T TO	5/20 18/2 5HC	362 75/hb	53/2 58/2 59/1	46/52/7/92 17/63	2/2	86/28 2/6 26/20 5/4	E Se Se	44/5271/34 7265 80/101	5/43 5/4C 5/41				O
Speed	3	70 70	, 09	S	0	10	179	79	64	29				
Record No.	4827	1823	756h	1293	430	(491Z	大路5	(38)	24.46	SE				
me me	(ZX) 5<:51	58h 583	28 12 13:41) 4322	然 [2]34] 4393	15:19 43)0	15:19 (4912	15:32 4.884	(26), 75:51	94.95 94:51	15:46 5645				165
Pass	60	2	7.5	7.18	19	5	30	C C	8	<u></u>	 			W X
Tuek	· massassas	ch		2	V Mario Milleryn	d	. Whiteles	رسم :	resolvesterning.	4				新水
Radar Speed	5	65	60	R	9	50	0	6	whatercaster	4				Recorded by
Pvmit	20	J.	47.7	\$ 5.5 S	4	7	r L L	n G	7	ğ				Record

6420070022_SPSWIM_TO_15_51_2.119_0100_pre-Validation_sheet_21

Section With States Test Residence Life Lot Lo						Sheet 21)]					*ST	* STATE_CODE)DE			4.7		
State Truck Pass Truck Records 1 of 1						[PP Traffi	ic Data					*SPS	PROJE	CT_ID		i	0 0 9 0		
Stand				WIM Sy.	stem Test	Truck Re	cords	to j	***************************************			* DA	UTE		121	1 1	2008		
Since Since Since Flats Truck Plats Truck	Rev. 08	3/31/2001									, 4. Z								
5 55 2 Birthogogg 56 3/65 5/78 7/88 7/89 7/99 1660 H16 413 21.0 5 55 1 Birthogogg 56 3/45 7/87 7/88 7/99 7/99 1660 H16 413 21.0 5 55 2 2 History 146 58 3/45 7/87 7/88 7/99 7/96 1653 H15 4.3 21.0 5 52 1 2 History 146 58 3/45 7/87 7/88 7/99 7/99 177 7/8 14.9 41.4 21.6 5 62 2 History 146 58 3/45 7/98 7/98 7/99 7/99 177 7/8 15.0 41.4 21.6 5 62 1 H History 146 50 4/47 7/88 7/98 7/99 1/99 1/99 1/99 1/99 1/99 1/99 1/99	Pvmt temp	Radar Speed	Truck	Pass	Time	Record No.	WIM Speed	Axle A weight.	Axle B weight.	Axle C weight.			Axle F weight	GVW	A-B space	B-C space	C-D space	D-E space	E-F space
5 55 1 1 13:45.90.89 57 514.87 78.5 84.5 87.8.2 77.8 14.9 444 21.6 5 57 2 2 14:00.9146 58 574.9 576.2 878.2 878.2 77.8 14.5 4.3 24.0 5 57 2 2 14:00.9146 58 574.9 576.2 878.2 878.2 77.8 15.5 4.4 21.6 5 56 1 2 14:00.9147 59 48.0 76.0 78.0 76.2 17.8 15.5 4.4 21.6 5 56 2 4 14:00.9149 59 57 594.0 576.2 78.0 78.2 879.2 72.7 15.0 4.4 21.6 5 56 2 4 14:00.9149 56 576.0 576.0 78.0 78.0 78.2 879.2 17.5 15.0 4.4 21.6 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 76.0 14.6 4.2 21.0 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 78.0 17.5 15.0 4.4 21.6 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 78.0 17.5 15.0 4.4 21.6 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 17.5 15.0 4.4 21.6 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 17.5 15.0 4.4 21.6 5 57 1 5 14:00.9149 60 576.0 78.0 78.0 78.0 78.0 17.5 15.0 4.4 21.6 5 6 7 1 6 14:59 9475 65 574.0 78.0 78.0 78.0 78.5 78.0 12.0 14.0 12.0 16.0 14.0 14.0 14.0 14.0 14.0 14.0 14.0 14		<i>R</i> ,	CP		13:45	806	-9	200	23/62	54/58	76/20	36		0.99				43	
5 52 2 2 14:00 9146 58 5940 5662 5452 876 65.8 14.5 4.3 24.0 5562 54.0 5762 67.0 57.0 4.4 21.6 5562 2 4 14.2 21.6 5562 2 16.2	70.00	B	<i>*</i> :		57:8	9539	Sec.	5/18	128	73/5	28/2	82/22		27.8	14.9	1	2:17	七十	
5 52 1 2 3 14:009147 59 4849 769 7848 7244 768 77.2 15.0 4.4 21.6 5 62 2 4 14:009147 59 4849 769 56,0 7091 769 66.3 14.5 4.3 22.9 5 62 2 4 14:0093939 57 5849 562 769 769 769 66.3 14.5 4.3 22.0 5 56 2 4 14:0093939 57 5849 562 769 769 769 76.7 15.0 4.4 21.6 5 56 2 4 14:0093939 57 5849 562 769 769 769 76.7 16.6 4.4 21.6 5 58 2 5 1 1 4 14:0093943 60 51/49 562 57/8 562 763 16.0 14.6 4.2 21.0 5 62 2 6 14:0093943 60 47/49 768 769 769 769 769 769 769 769 769 769 769	(F. 5)	6	C	d	支 6 5	2176		53/20	121	20/13	C8/8	28/sc			***************************************	3		÷	
5 62 2 3 1415 9243 62 5148 950 51/60 8091 7492 66.3 145 4.3 20.3 15 56 2 4 447 7388 990 8298 8090 76.2 145 4.3 20.3 15 56 2 4 447 7388 990 8298 8090 76.2 14.6 4.3 21.0 15 56 2 4 4 14.20 93.04 57 5940 56.2 5940 56.2 5940 56.2 14.6 4.3 21.0 15 57 1 5 14.40 9490 60 51/40 51/60 890 57 5940 56.2 14.40 7490 975 60 51/40 74	0		<u>,</u> _	d	14:00	5		4849	16/9	73/86	May 1	25/28			0,5/		1	÷	
5 56 2 4 14:29 3245 62 444, 7388 7/20 82/28 82/57 76.7 15.0 44.4 21.6 5 56 2 4 14:29 3394 56 47/28 87/20 87/20 21.0 14.6 4.2 21.0 5 56 1 4 14:29 3314 56 47/28 87/20 87/20 87/20 17.5 15.0 44.4 21.6 5 57 1 5 14:42 94.2 60 57/40 57/10 57/20 87/20 87/20 87/20 17.5 15.0 44.4 21.6 5 57 1 5 14:42 94.2 60 57/40 57/20 87/20 87/20 87/20 17.5 15.0 44.4 21.6 5 62 2 6 14:57 94.6 63 57/20 27/20 87/20 73/20 73/20 17.5 15.0 44.4 21.6 5 62 2 6 14:57 94.6 63 57/20 74/20	R N	S		({ })	15 A			5	No.	29/25		63/20						n	
56 2 4 14:20 33.03 57 59/42 57/62 74/02 75/22 66.1 14.6 4.3 21.0 56 1 4 14:20 3314 56 47/43 75/82 87/53 87/33 77.5 15.0 4.4 21.0 5 57 1 5 14:42 9402 60 57/42 75/82 87/53 87/42 77.5 15.0 4.4 21.0 5 57 1 5 14:43 943 60 47/42 75/82 87/53 87/52 75/82 75	S		v d ^{a d} ampin miyangda	7	7:3			44	73/88	100	200	8/		76.7				かず	
5 58 7 5 1 14:29 2314 56 47/43 788 786 84/53 77.5 15.0 4.4 21.6 5 58 7 5 1 5 14:42 9402 60 51/49 55/1 54/5 806 77/38 66.7 14.6 4.2 21.0 5 57 1 5 14:42 943 60 47/4 3/59 7/34 81/3 81/24 77.3 15.0 4.4 21.6 5 57 1 5 14:43 943 60 47/4 3/59 9/55 3/59 20 20 20 6.0 14.6 4.2 21.0 5 62 2 6 14:57 9468 63 59/48 53/2 52/1 828 3/50 66.0 14.6 4.2 21.0 5 63 1 6 14:57 9475 65 47/4 7/39 69/8 5/55 7/50 76.5 17.5 17.0 4.4 21.6	4	70		7	14:25	Eb		50/20	25/62	52/6	06/2/	15/27		1.9		23		in the	
5 58 2 5 14:42 9402 60 3/49 5/1, 5/6, 8% 7/88 66.7 14.6 4.2 21.5 5 57 1 5 14:42 948 60 474, 3/8 7/84 8/3 8/34 77.3 15.0 4.4 21.6 5 62 2 4 6 14:59 948 63 5/48 5/43 3/4 8/35 8/36 66.5 14.6 4.2 21.5 5 62 2 6 14:59 9475 65 4/49 7/89 9/85 7/36 76.5 15.5 4.4 21.6	2	25	menekirte-	3	3:			47/43	28/2	75/86	35/48	84/93	R	20.	150	ナ	7.6	3-	
5 57 1 5 14:43943 60 474 3/19 7/84 8/13 8/24 77.3 15.0 4.4 21.6 5 62 2 2 6 14:59948 63 548 53/2 54, 30/2 3/2 15,0 4.4 21.6 5 63 1 6 14:59945 65 474 789 6/2 5/2 3/2 15,0 4.4 21.6	435	η) δο	رحل	ហ	5.	9467	G	5/2	35%	54/00	E	28/1		(79			23	ナナ	
5 62 2 6 14:59 94:3 63 54:8 54:3 54:1 30/2 73/2 14:6 4:2 31:0 5 63 1 6 14:59 9475 65 4745 7485 9/85 73/2 12:0	£ 50		1 €woodenshii	M	Chit	25		12/4Z	200	12/27	187	E ST	5	27.3			7	3	
83 L 2 6 14:57 9468 63 59/18 52/2 52/1 30/2 3/2 66.6 14.6 4.2 21.0 5 63 1 6 14:58 9475 65 47/4 7482 67/8 8/2 5/2 6/2 12.6		S.	4		4	\$ 68°		The state of the s	98/12	2) 53	\$ 1.00 m	Sel Sel	3	Service of the servic					
5 62 2 6 14:57 948 63 5948 5363 526 66.0 14.6 4.2 21.0 5 63 1 6 14:58 9475 65 4749 7489 9785 7965 72.5 15:0 4.4 21.6		S	7	S	***************************************		128												
5 63 1 6 14:58 9475 65 49/48 89/8 82/5 22/56 414 21.6		7	\ C\(\)	9	4:50	9468	α	20/18	53/63	2/1	80/29	P. P.		·	1	Į	·	23	
		2	T-244	6	, ,	(F)	W	42/42	1889	8/0	20/2	79/56		5.2	·····			3	
										•	٠,								
											•								

Checked by_

Recorded by MAPK 3

6420070022_SPSWIM_TO_15_47_2.118_0600_Cal__ sheet_21.doc

Sheet 21	* STATE_CODE	51
LTPP Traffic Data	*SPS PROJECT_ID	0100
WIM System Test Truck Records	* DATE	1000 D 10 14 T

Rev. 08/31/2001

E-F space															
D-E space	Lan	3	and a second	7	5	3	ゴ	J.	7	40	3	Z,	3		
C-D space	7.6	2.2	216	7.0	е Б	25.0	2.5	100	0 1	0 77	0	i	<u>0</u>		
B-C space	<i>j</i>	9	7	7	3	3	グチ	3	3- 3-	5	ナデ	23	3		
A-B space	30	3	0,0	9:41 9:99	000	5.5 9.5	2	3	r.	7	らい	チ	2		
ĠΛW	N N	7.00	0.50	66.6	N	800	2,7	57 7 60	72.0	do Lj	132	27.00	2.6		
Axle F weight															
Axle E weight.	06/70		200	75/32	20/20	7,88	13/8	180	78/2	The state of the s	56/2c		1000		
Axle D weight.	00/500	26/12	E Contraction of the contraction	187	7/18/28/	75/87	200	2000	2012	Elsi	36/88 62	2/20	20/02		
Axle C weight.	7485 G/87	Ž a	35 68/85	27/15	50	72,	787	16/C 56/6 17/15 27/25	185 S	73/2	100		963		
Axle B weight.	74/85	2/62	28/25	19/6 H	16 BK	2%3	200	77/25	26	20	75/20	20	3/65		
Axle A weight.	4943	Tin Time	Ch/2	46/24	45/5)	4852	2/10	3/2	85/0g	752		49/	3/2		
Speed	3 V)	J.	29	b	63	G	ŭ	N	9	50	S	62	P.		
Record No.	545	1245G	12485	8HZ	1.855	1288	61771 4-2	[727]	07	7237	020	12748	1287		
Time	7:58	7:58	8:13	<u>6</u>	27.3	8:24	4	21:00 1:00	ў. Ю	TY:00	00%	80%	23.27		
Pass	7	1	Cψ	αģ	ಯ	Ø	٥	<u>Ø</u>	707	-	Œ	Q	W	<u>Q</u>	
<u>720</u>	700000000000000000000000000000000000000	c-(s	N. T. S. M. S.	d	Character Street, ag	d	. Sheeded on Eg	d	**************************************	٦	paninaniinining.	d	5	Ø _p	
Speed	4	Ŋ	K)	0 10	Williamson	n) W	63	7) (3)	17.2) 2)	G	9		C.M		
Pvmt	S	Ŋ	K K	K K	5. pi	8. N	S S	3.	(J)	(A)	66 86	60 80 80	r V		

Checked by_

Recorded by MARK 3

 *%.				E-F spac
		0 <2		D-E space
51	0100	007		C-D space
		8001/20/4/	Name 100	B-C space
		121		A-B space
ODE	CT_ID			@VW
LATE_C	*SPS PROJECT_ID	* DATE		Axle F weight
S*	*SP	Q*		Axle E weight.
				Axle D weight.
 . *				Axle C weight.
		الم		Axle B weight.
		7 Jo 2		Axle A weight.
	c Data	cords		WIIM Speed
Sheet 21	LTPP Traffic Data	Truck Re		Record WIM No. Speed
***************************************	LI	tem Test		
		WIM Sys		Truck Pass Time
		,		Tuc.
		į	Rev. 08/31/2001	Radar Speed
		j	Rev. 08	Pvmt

		· · · · · · · · · · · · · · · · · · ·	γ	·		· · · · · · · · · · · · · · · · · · ·	τ	1	· · · · · · · · · · · · · · · · · · ·	.,	·	- J	·		· · · · · · · · · · · · · · · · · · ·		7
E-F space																	
D-E space	ナナナ	2. W	entitions.	2	7	ro F	7.7	25	- Jan	4 0	3		g	n	in and a second	3	
c-D space	<u>U</u>	<u>2</u>	10	mou.	7	0	P. F.	00	7.77	ä	2 2	Ä	d	9	<u>3</u>		-
B-C space	<u>ئ</u> ئ	2 2	<u> </u>	n t	3	6.3	き	3	き	7. Wi	3	3	3 5	and and	22	j	
A-B space	<u>5</u>	7	N	3 5	0.50	79	<u>n</u>	97	10. 0.	2.50	500	7	变	3	70	237	-
@WW	3,6	57.6	7.2	(10)	200	8.30	26.5	57.6	3	2.3	7.0	0.99	76.3	07.60	16.8	6.33	
Axle F weight																	
Axle E weight.	8/0	PEEC	824	No.	26/18	15/29	200	OFFIC	8//20	76/35	280	100 mg	100, 100, 100, 100, 100, 100, 100, 100,	<u>0</u>	25/18	26/2	
Axle D weight.	85/92	32/1	84/2	78/53	25/23	63/20	72	100	85/12 81/20	76/36 July	26/20	K. J.	82/1 192	87 88	16/28	81/20	
Axle C weight.	\$	A STATE OF THE PARTY OF THE PAR	25	564	25	23/2	Spey	25	72/84	2/62	56/29	T. C.	69/85	5/2/20	28/25	E ST	
Axle B weight.	75/		To the second	51/69	06/92	200	74/6	34/1/2	2	E7/15	38/3	36	80/2 1/2	Y 50	182	52/30	
Axle A weight.	48/45	S S S S S S S S S S S S S S S S S S S	at B	2/27	Ser.	#352	53/49		37	55/54	34	2. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	948	575	50/48	22	
WIM Speed	N	J V3	E	か	65	4	5	苏	9	59	66	to	ふ	S	9	D.	
Record No.	(0)	000	192	999	5	2	764	22	0	818		803	1830 1830	かった	[00]	gs g	
Time	7:07	25	is is	917	87:7	23	and the same	C)	2	12:56	13:08	13:09	200	27:2	Š	J. 55	
Pass	(7)	- Jan	and the same	12	ŢŪ	9	(a)		r	D00	6 0	13	K	20	S	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
Truck	of the designation of the	<i>C-6</i>	The state of the s	d	4 photography	CP	the trademost delices.	d	Artife & Jacobson .	K	dephasemakais.	cl	Marienzania	i. V	a. Salaharan	6.8	
Radar Speed	N	\mathcal{C}	0	82	t		B	ň	9	N 80	T	S	ß	Ž.	3	3	
Pvmt temp	S	r R	200	is the state of th	W	Ñ	S. Š	(5) (7)	53,5	EX. N	G	Q	49.0	Ž.	R N	以 以	

6420070022_SPSWIM_TO_15_51_2.119_0100_post-Validation_sheet_21

Checked by __

Recorded by MARK Z

Calibration Worksheet

Site: 510100

Calibration Iteration Date 12 3 / 00

Beginning factors:

Speed Point (mph)	Name	Value
Overall		1 * 2
Front Axle	dynamic confingation	445 loo
1-(45)	72 404	3575
2-(65)	88 / July	357.5
3-(1)	104 Koh	3565
4-(86)	121 Koh	3565
5-(QG)	137 WOL	3565

Errors: 35 60 65

	Speed	Speed	Speed	Speed	Speed
	Point 1	Point 2	Point 3	Point 4	Point 5
F/A		+ 2.3	*1.0	-0,9	
Tandem		45,3	45.3	* ¥.6	
GVW		+4.7	+ 4.4	+3,5	

Adjustments:

	Raise	Lower	Percentage
Overall			
Front Axle	Ø		3,0 %
Speed Point 1			- 4.0%
Speed Point 2		\square	- 4.0 %
Speed Point 3			-4.0%
Speed Point 4		Ø	<u>-4000</u>
Speed Point 5		Ø	-4.0%

End factors:

Speed Point (mph)	Name	Value
Overall		
Front Axle	dynamic candensition	103
1 - (५५)	12 kph	3422
2-(65)	68 KgV	3422
3-(15)	log kip	3422
4-(85)	121 Juh	3472
5-(95)	137 Wh	3422

TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

December 2, 2008

STATE: VIRGINIA

SHRP ID: 510100

Photo 1 - Truck_1_Tractor_ 51_0100_12_2_09.JPG	. 2
Photo 2 - Truck_1_Trailer_Load_1_51_0100_12_2_08.JPG	
Photo 3 - Truck_1_Suspension_1_51_0100_12_2_08.JPG	
Photo 4 - Truck_1_Suspension_2_51_0100_12_2_08.JPG	
Photo 5 - Truck_1_Suspension_3_51_0100_12_2_08.JPG	
Photo 6 - Truck_2_Tractor_51_0100_12_2_08.JPG	
Photo 7 - Truck_2_Trailer_51_0100_12_2_08.JPG	
Photo 8 - Truck_2_Suspension_1_51_0100_12_2_08.JPG	
Photo 9 - Truck_2_Suspension_2_51_0100_12_2_08.JPG	
Photo 10 - Truck 2 Suspension 3 51 0100 12 2 08.JPG	



 $Photo\ 1\ \hbox{-}\ Truck_1_Tractor_\ 51_0100_12_2_09.JPG$



Photo 2 - Truck_1_Trailer_Load_1_51_0100_12_2_08.JPG



Photo 3 - Truck_1_Suspension_1_51_0100_12_2_08.JPG



Photo 4 - Truck_1_Suspension_2_51_0100_12_2_08.JPG



 $Photo\ 5\ -\ Truck_1_Suspension_3_51_0100_12_2_08.JPG$



Photo 6 - Truck_2_Tractor_51_0100_12_2_08.JPG



Photo 7 - Truck_2_Trailer_51_0100_12_2_08.JPG

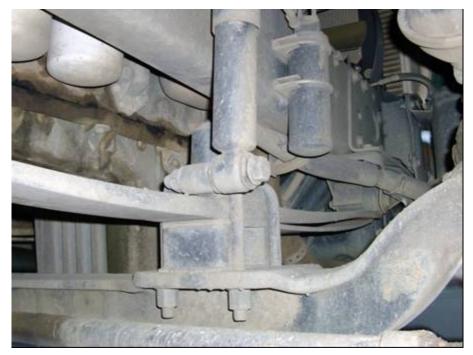


Photo 8 - Truck_2_Suspension_1_51_0100_12_2_08.JPG



Photo 9 - Truck_2_Suspension_2_51_0100_12_2_08.JPG



Photo 10 - Truck_2_Suspension_3_51_0100_12_2_08.JPG

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *			-			2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
Spacing 8																														3.00-45.00
Spacing 7																													3.00-45.00	3.00-45.00
Spacing 6	77711														***************************************													3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						700000000000000000000000000000000000000						, , , , , , , , , , , , , , , , , , ,														2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00 - 10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	7	2	2	2	3	3	3	3	3	3	4	4	#	4	4	4	ĸ	\$	S.	w.	\$	5	S	9	9	r-	90	9
Vehicle Type	7	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/ I Axle Trailer	Other w/ 1 Axle Trailer	Bus	2D w/ 1 Axle Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	60	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	3

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

Virginia SPS-1 (Lane 1)

Validation Visit – 4 December 2008

Calibration factor for sensors #1 & 2:

	December 4, 2008	December 2, 2008	July 25, 2007
Dynamic			•
compensation	103	100	
72 kph	3422	3565	3700
88 kph	3422	3565	3700
105 kph	3422	3565	3700
121 kph	3422	3565	3700
137 kph	3422	3565	3700